



Evaluating Persistence Times in Populations that are Subject to Catastrophes

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Intro 1: Queues vs. Populations

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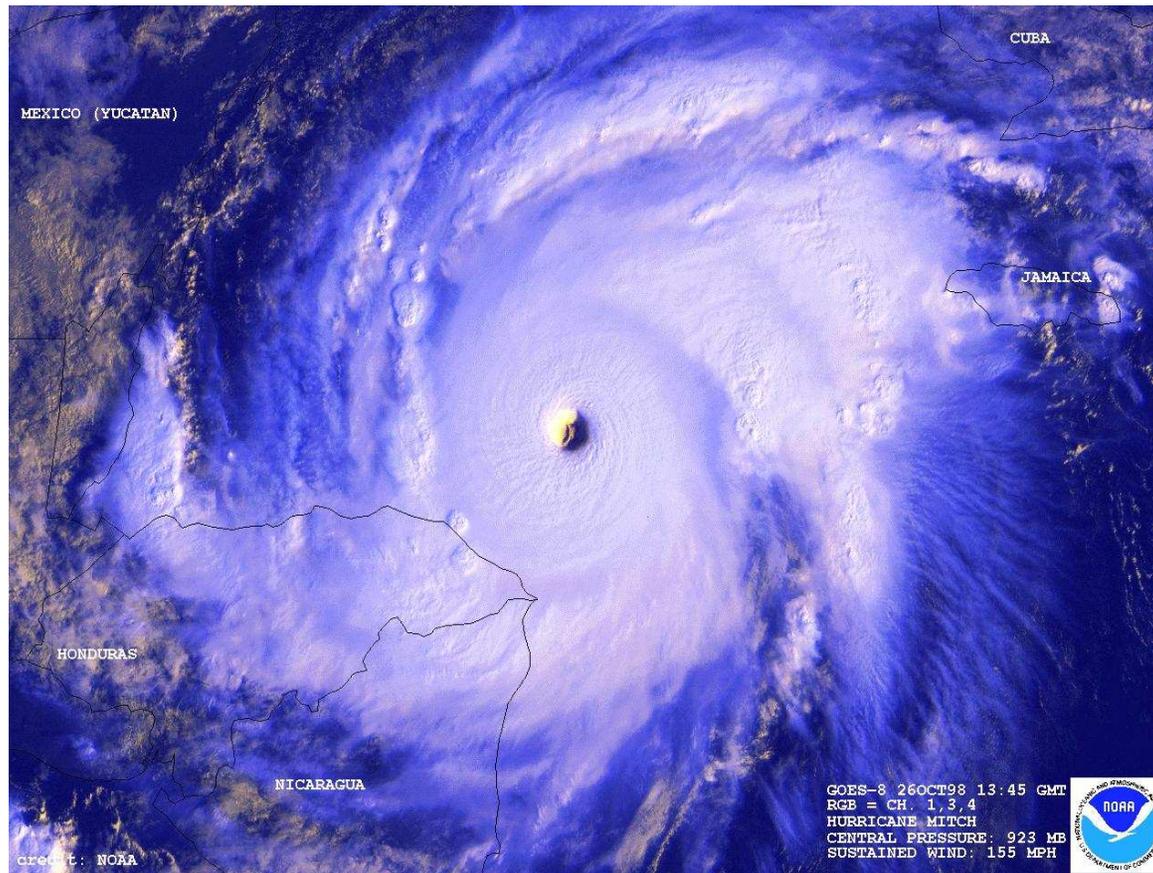
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- Of course, any biological population experiences **births** and **deaths**.
 - (c.f. *birth-death processes*.)
- Some populations may also experience **catastrophic** events, which may cause large numbers of deaths.

Introduction: Catastrophes



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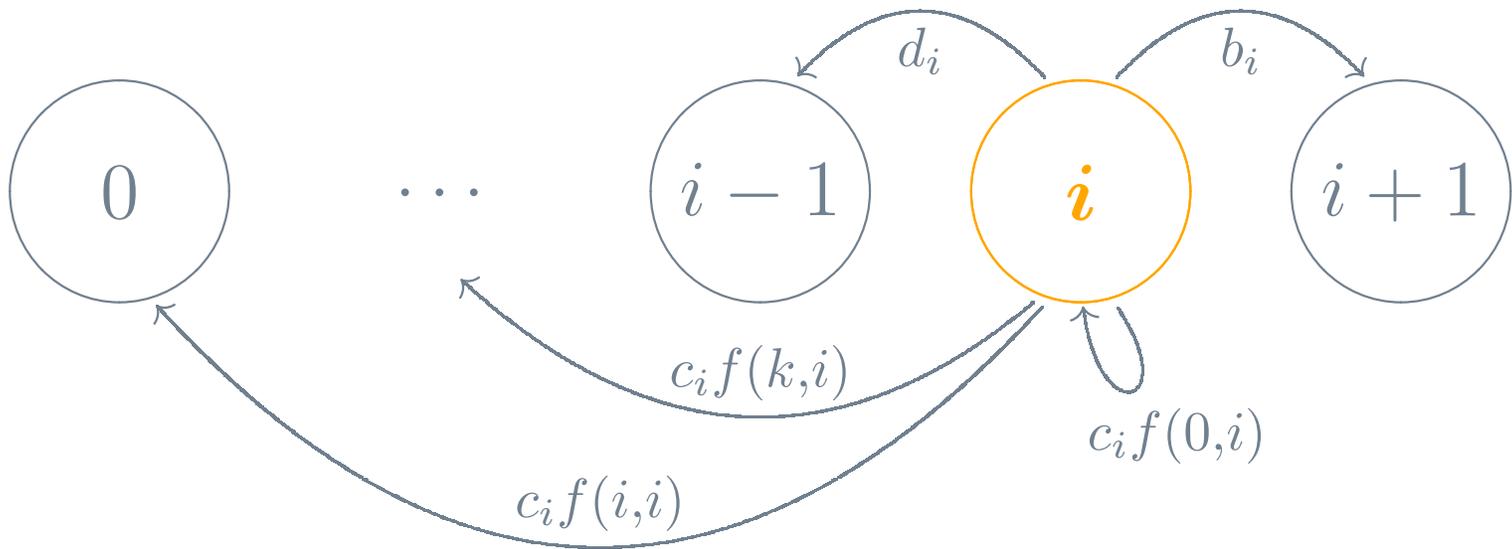
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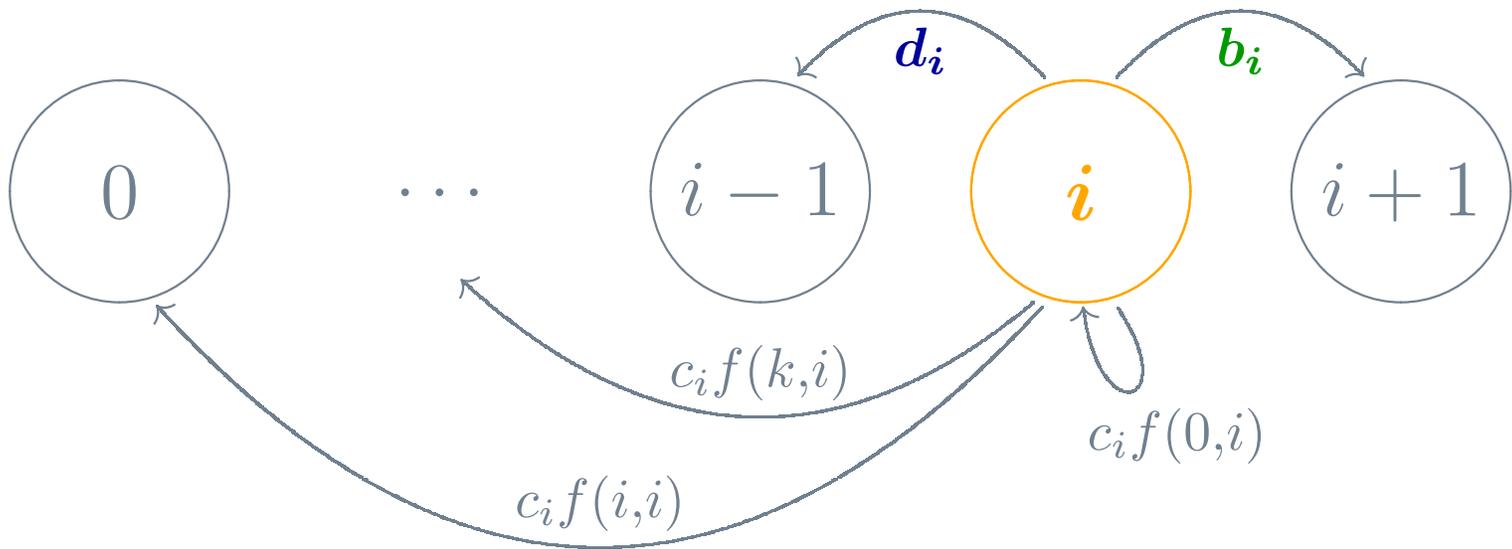
We will define *continuous-time Markov chains* exhibiting transitions corresponding to each of these events:

birth, death and catastrophe processes.

BDCPs

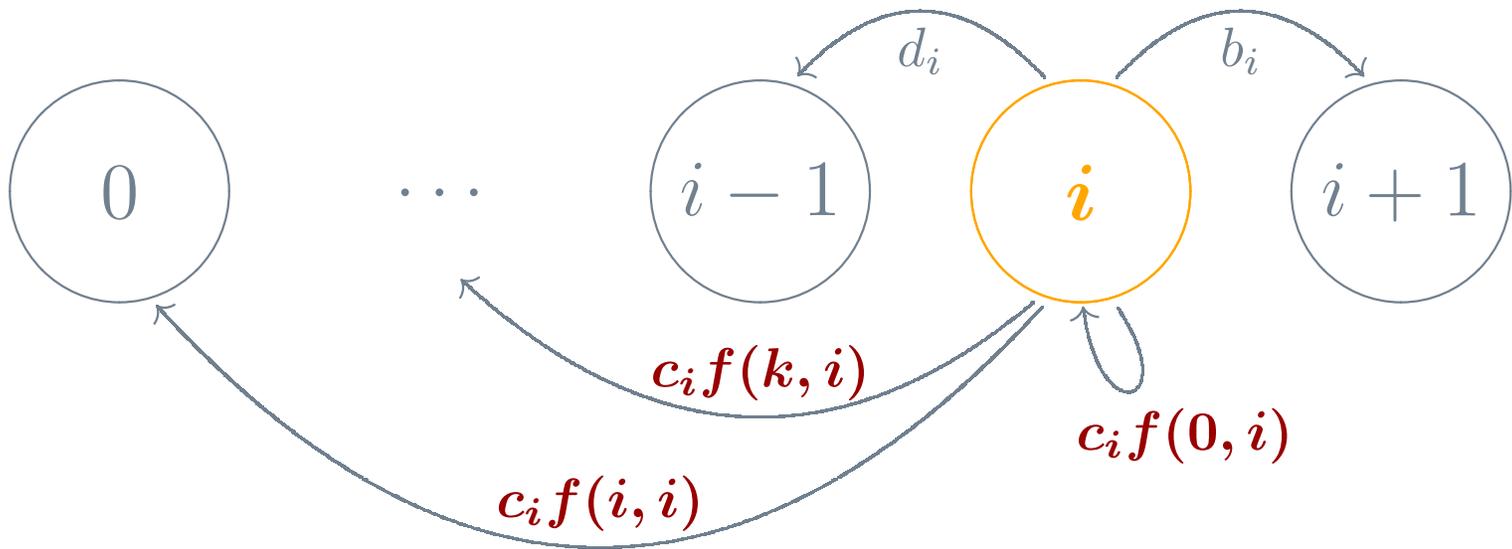


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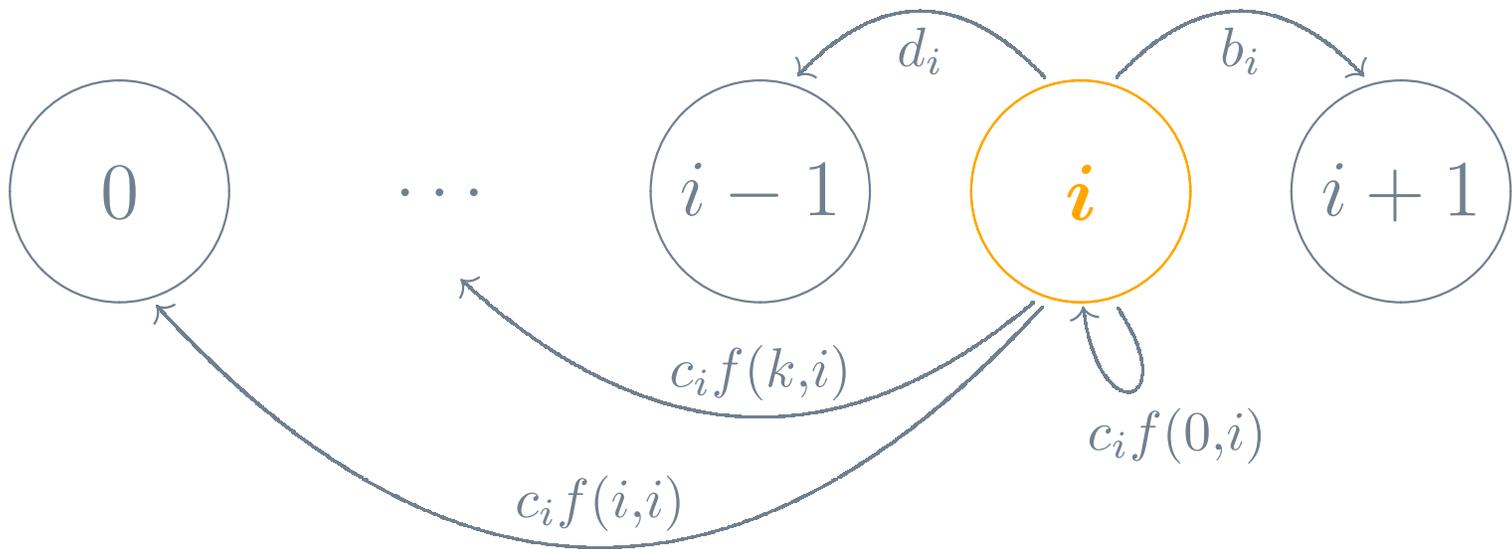
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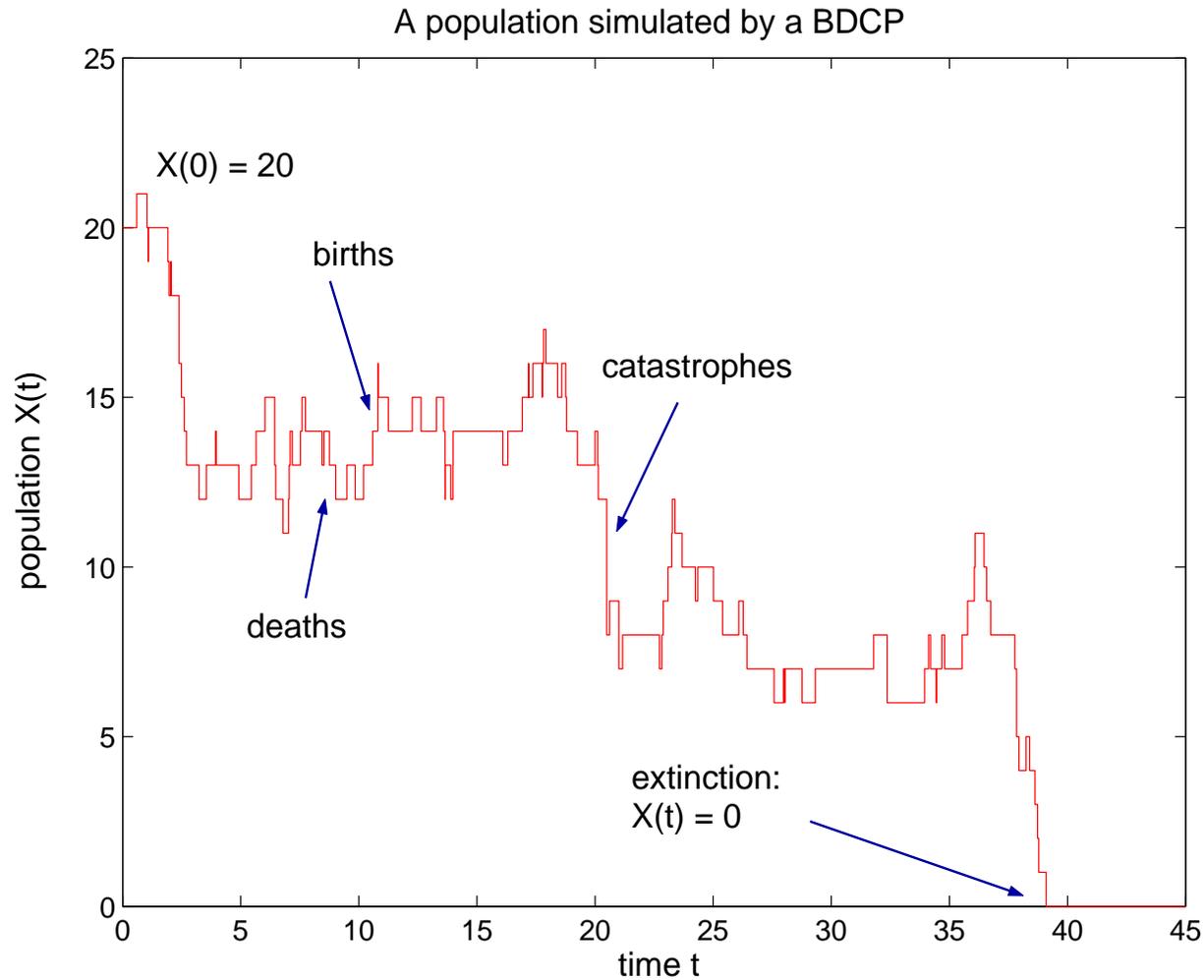
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- Births occur at rate b_i , deaths at rate d_i .
- Catastrophes occur at rate c_i , killing k with probability $f(k, i)$.
- We express these transitions as rates q_{ij} from i to j individuals.

$$\text{Rate } q_{ii} = - \sum_{j \neq i} q_{ij}.$$

A simulation example



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For **bounded** populations, extinction is certain: Solve

$$\mathbf{M}\boldsymbol{\tau} = -\mathbf{1}.$$

\mathbf{M} is the matrix of transition rates q_{ij} , with i, j restricted to between 1 and the upper bound N .

Unbounded populations

Even if there is no such bound N , extinction may be certain. Then, τ_i is the minimal, non-negative solution to

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In some cases, there are analytic solutions, but often this isn't possible—we need to find good approximations.

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Our goal is to solve the problem for the truncated process, and ensure it's a good truncation.

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And those of absorbing boundaries:

Pros

- + always underestimates τ_i ;
- + can see if A is suitable.

Cons

- apparently unrealistic;
- less easy to get approx. τ_i .

The character of solutions

Anderson (1991) characterised all solutions to the system

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(For τ_i , set $\theta = 0$, $\gamma_i = 1$, $z_0 = 0$.) All solutions have the form

$$z_i = a_i \kappa - b_i,$$

where $\{a_i\}$ and $\{b_i\}$ are unique sequences (see [And91] or [CP04]) and $\kappa = z_1$.

Choosing $A I$

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$\{\kappa_A\}$ is increasing, so $\kappa_A \uparrow \tau_1$ as $A \rightarrow \infty$, so if κ_A is close to τ_1 , approximate

$$\tau_i \approx a_i \kappa_A - b_i, \quad 0 \leq i < A.$$

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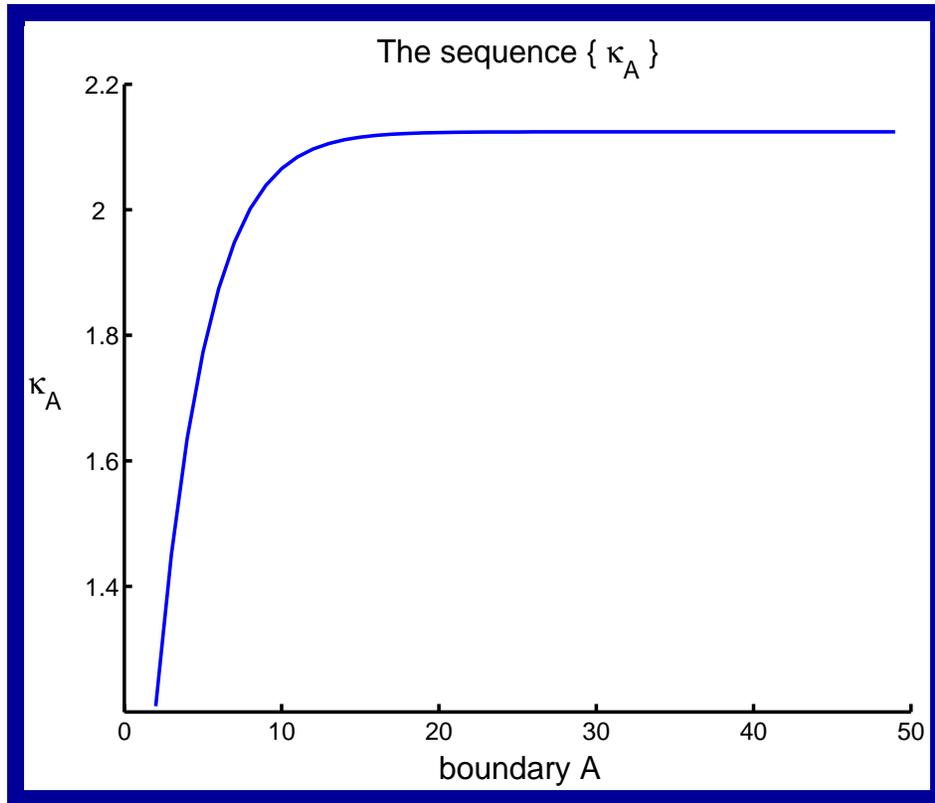
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BUT, we can check for apparent convergence of κ_A to some limit as A gets large.

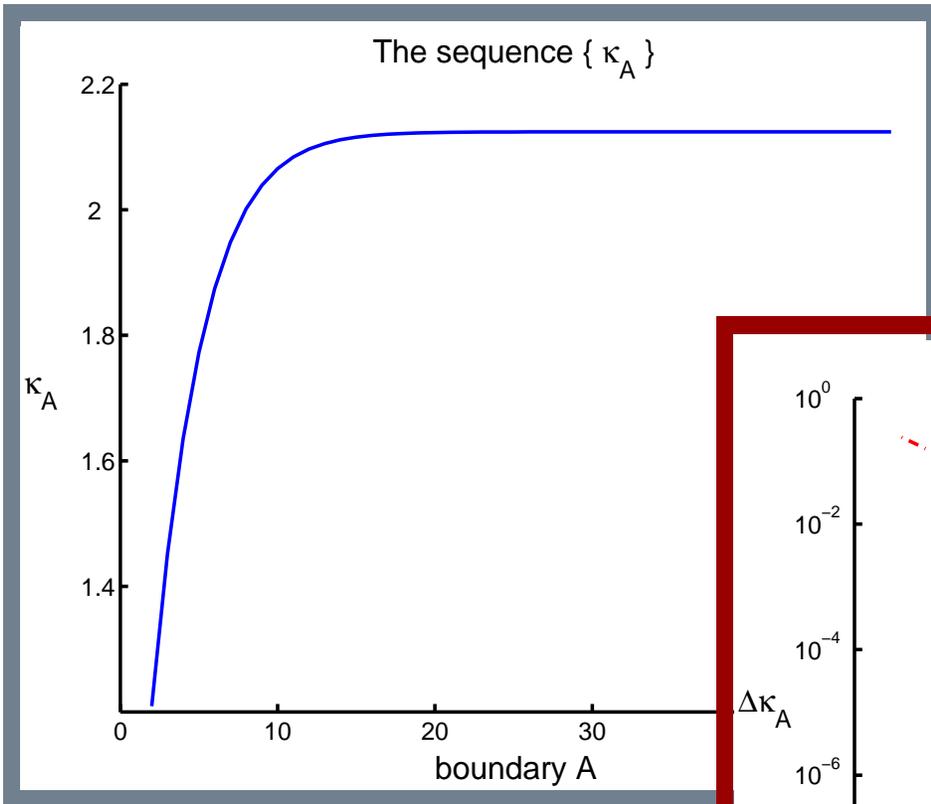
Convergence of κ_A



Example [CP04]:

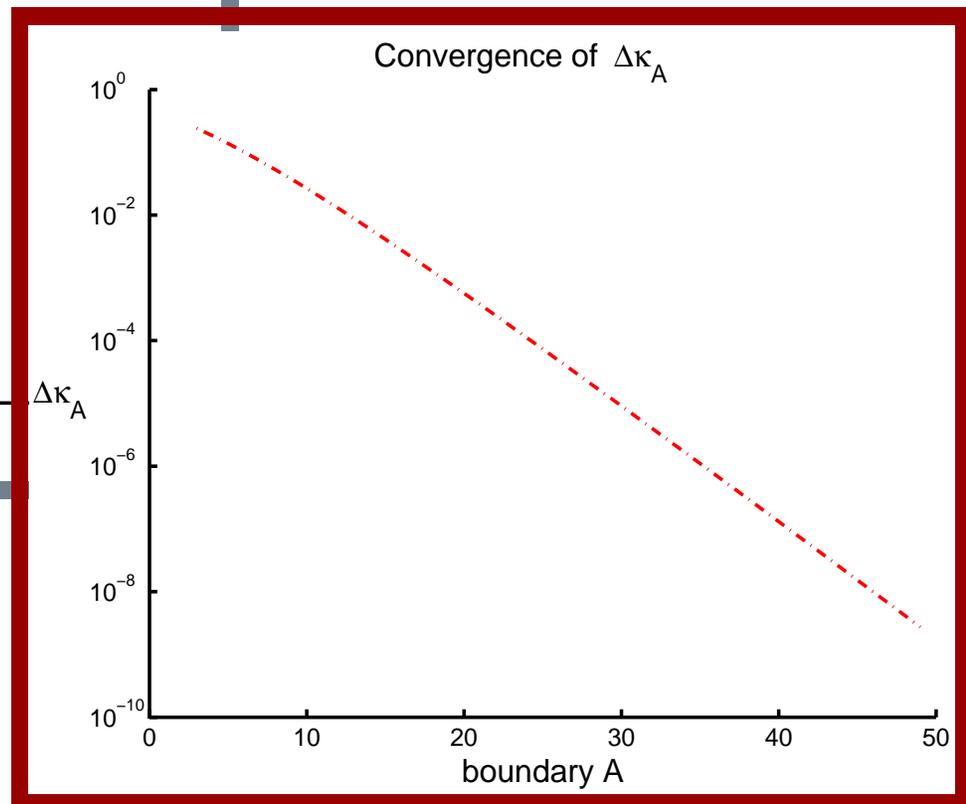
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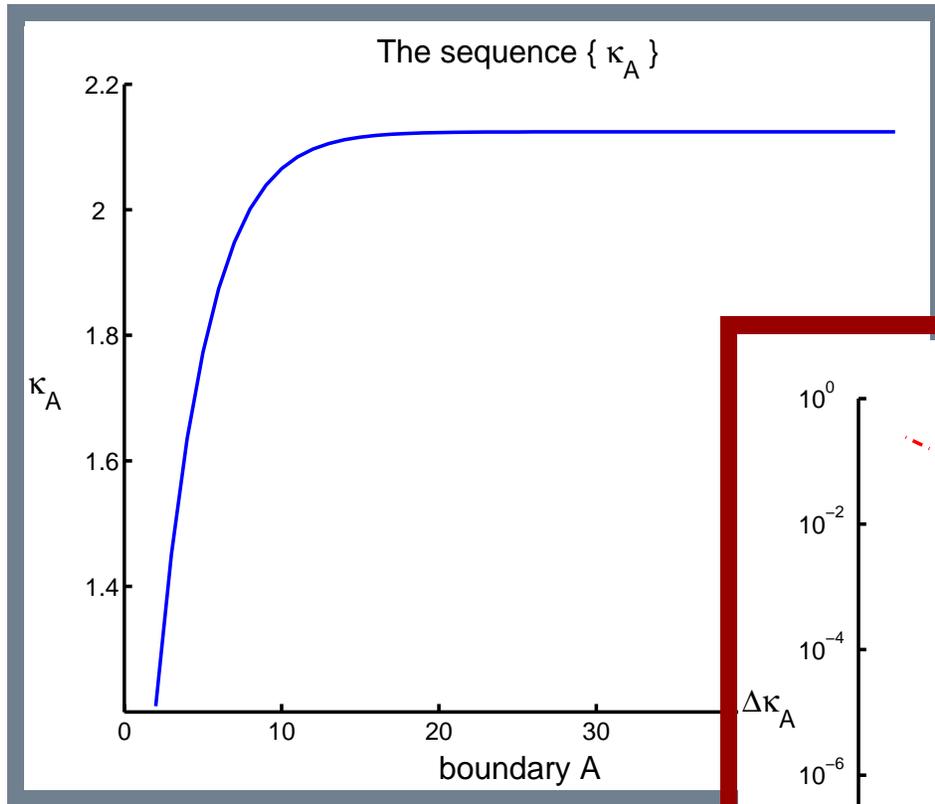
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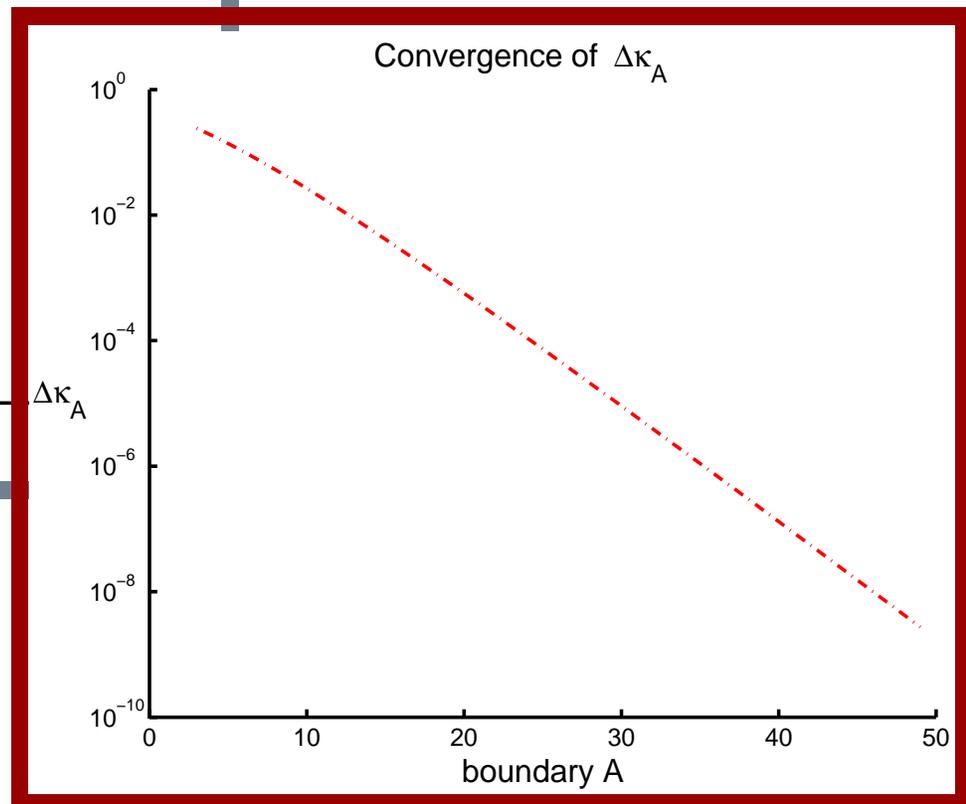
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We can reinterpret absorbing boundaries: κ_A gives the expected time to hit **either** 0 **or** A , starting with 1 individual.

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What if we take the (already) bounded process and make the boundary **absorbing**?

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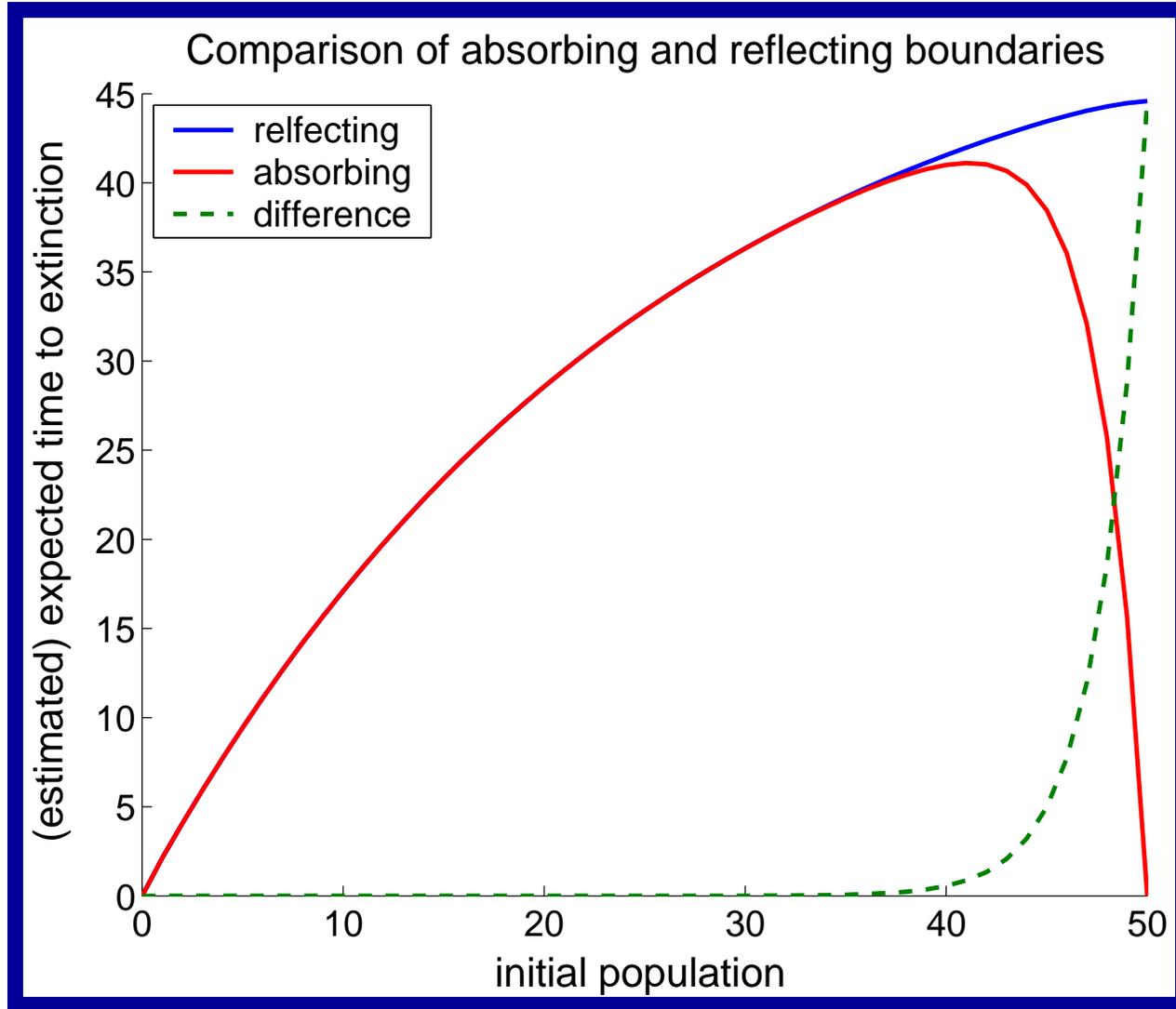
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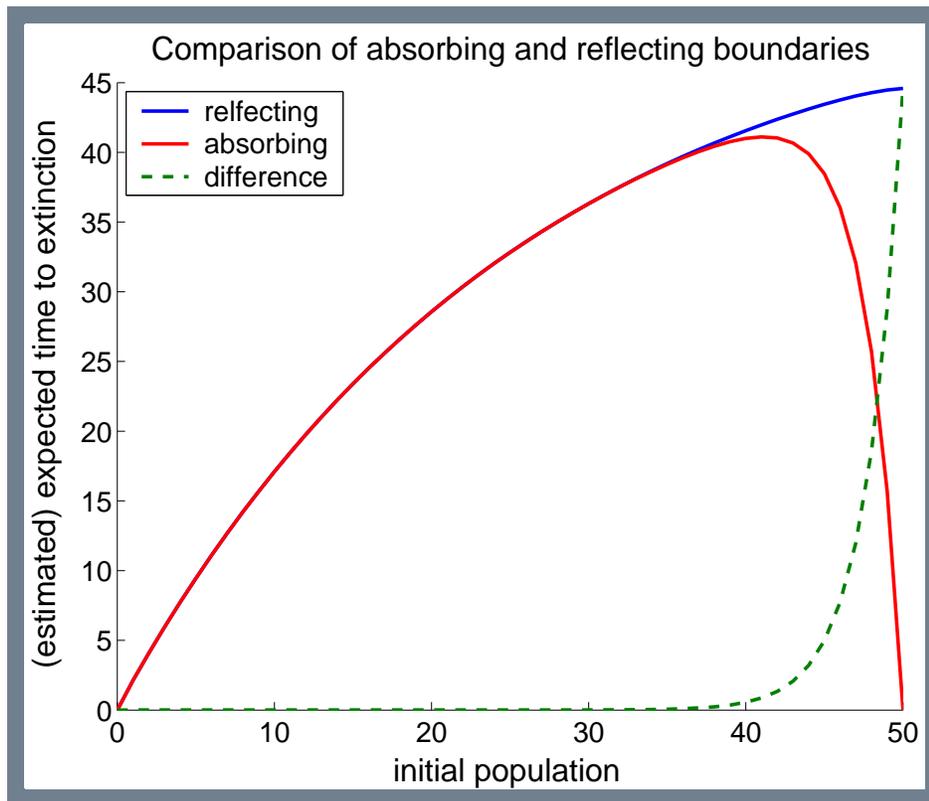
- understand how existing, physical bounds on population size affect persistence;
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Compare absorbing and reflecting boundaries to see if the boundary plays a significant role in the population process.

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The difference between the two results is the contribution to the extinction time, in the reflecting case, from the event that the population hits N **at least once** before extinction.

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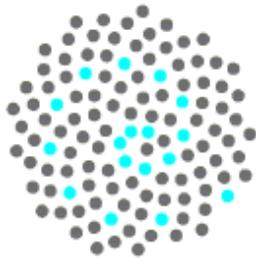
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 - Persistence of populations can be (relatively) easily assessed from model parameters.
- In some cases, truncation is necessary:
 - Reflecting boundary: simple, but may give over- or under-estimates.
 - Absorbing boundary: counterintuitive, but reliably underestimates persistence.
- Both can be compared to assess the effect of the boundary on persistence.

Thanks

- AMSI and ICE-EM.
- Phil Pollett and Hugh Possingham (advisors).



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References

- [And91] W.J. Anderson. *Continuous-Time Markov Chains: An Applications-Oriented Approach*, Springer-Verlag, New York, 1991.
- [CP04] B.J. Cairns and P.K. Pollett (2004). Approximating measures of persistence in a general class of population processes. (Submitted for publication.)

See also: <http://www.maths.uq.edu.au/~bjc/talks.html>