



Extinction in metapopulations with environmental stochasticity driven by catastrophes

Ben Cairns

`bjc@maths.uq.edu.au`

ARC Centre of Excellence for Mathematics and Statistics of Complex Systems.

Department of Mathematics, The University of Queensland.

Background and Summary

- Metapopulations are ‘populations of populations’, existing in a system of habitat patches:
 - *Example 1:* ... on ‘islands’.
 - *Example 2:* ... in successional habitat.
- Environmental events may reduce available habitat, which then gradually recovers.
- We will discuss a 2-D Markov chain model for a metapopulation, incorporating stochastic habitat dynamics driven by catastrophes.

Demographic Events

Paired metapopulation-habitat states make the following 'demographic' transitions:

$$(x, y) \rightarrow (x + 1, y) \quad \text{at rate} \quad r(N - x),$$

$$(x, y) \rightarrow (x, y + 1) \quad \text{at rate} \quad cy \left(\frac{x}{N} - \frac{y}{N} \right),$$

$$(x, y) \rightarrow (x, y - 1) \quad \text{at rate} \quad ey,$$

on $S = \{(x, y) \mid x, y \in \mathbb{N}, 0 \leq y \leq x \leq N\}$.

Catastrophic Events

Catastrophic jumps occur at a constant rate, γ , affecting each habitat patch independently:

$(x, y) \rightarrow (x - (i + j), y - j)$ at rate

$$\gamma \binom{x - y}{i} \binom{y}{j} p^{i+j} (1 - p)^{x-i-j}.$$

- p is the probability that each patch is rendered unsuitable by a catastrophe.

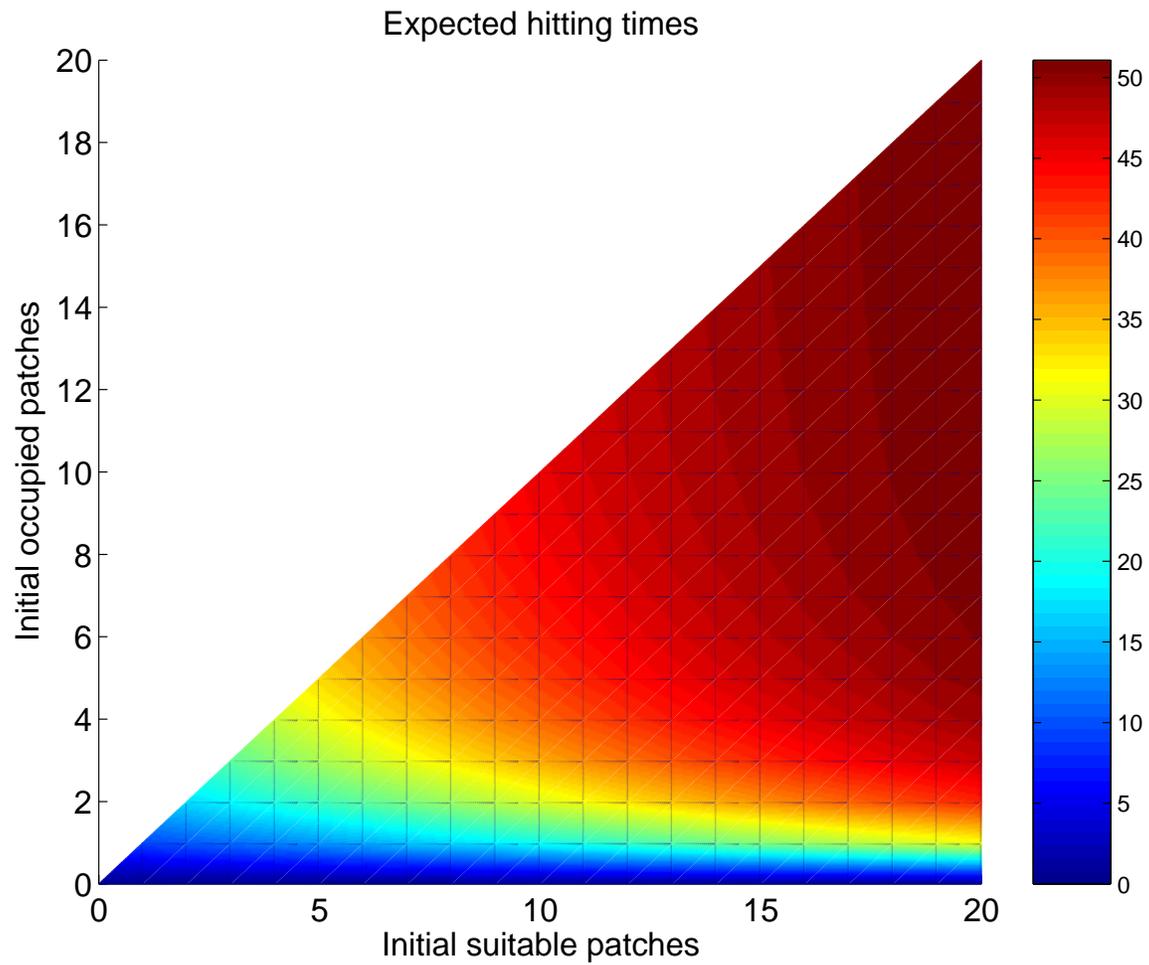
Finite State-space Processes

When N is finite, we can hope to evaluate measures of interest directly.

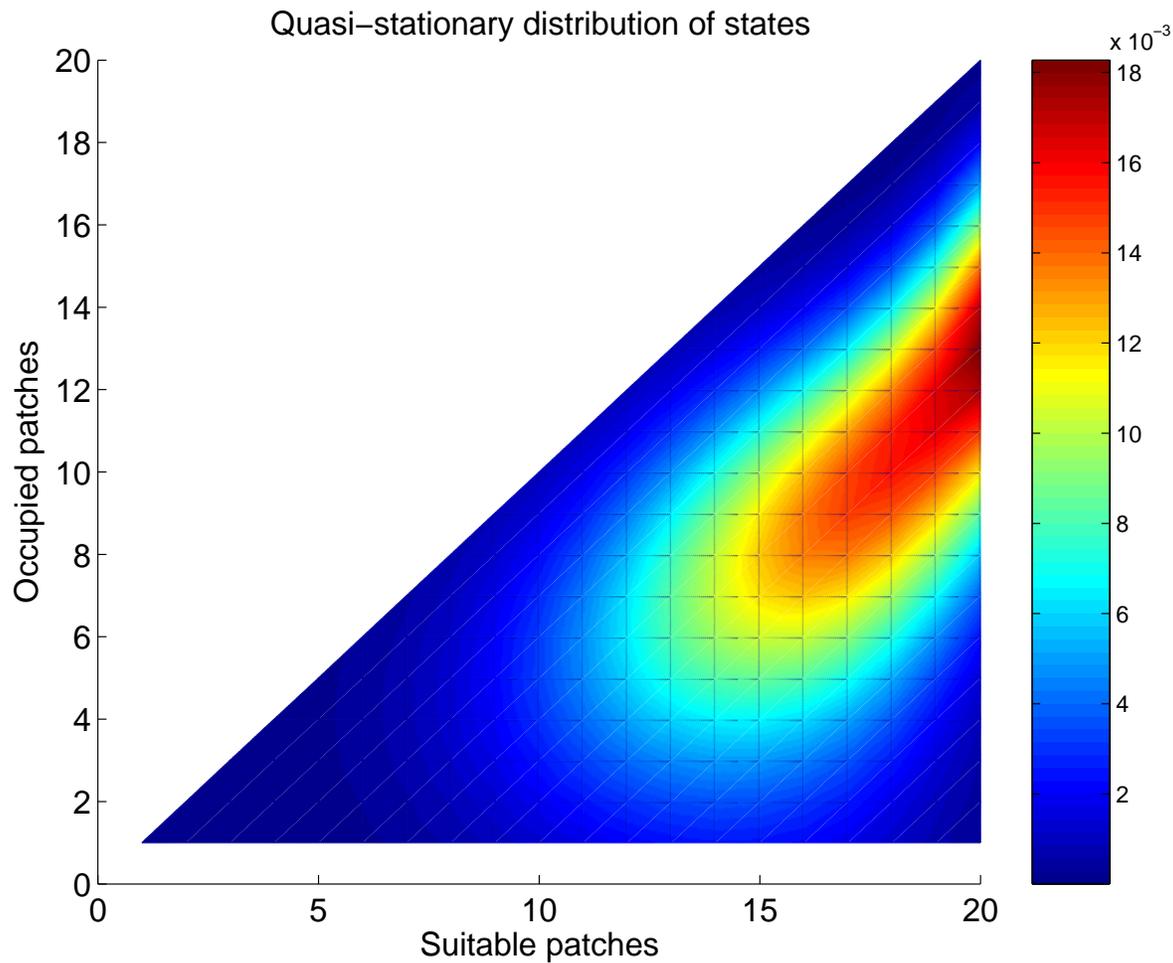
- Extinction (first passage) times are almost surely finite!
- Quasi-stationary distributions exist!

If these are easy to calculate (or approximate, e.g. matrix-analytic methods), we can use them to assess the characteristics of the system.

Extinction Times



Quasi-stationary distributions



A Deterministic Limit

- Assume for the moment that there are no catastrophes.
- It is possible to show that $\mathbf{X}(s, t)/N \rightarrow \mathbf{U}(s, t)$, which satisfies a system of ODEs:

$$\mathbf{a}(\mathbf{U}) = \begin{bmatrix} \partial u / \partial t \\ \partial v / \partial t \end{bmatrix} = \begin{bmatrix} r(1 - u) \\ cv(u - v) - ev \end{bmatrix},$$

with initial conditions

$$\mathbf{U}(s, 0) = \lim_{N \rightarrow \infty} \mathbf{X}(s, 0)/N. \text{ (Kurtz, 1970)}$$

Catastrophes in the Limit

- Treat catastrophes as a separate component.
- The arrival rate of catastrophes is unaffected by scaling.
- As $N \rightarrow \infty$, if T_1 is a catastrophe time,

$$\frac{\mathbf{X}(s, T_1)}{N} \xrightarrow{P} (1 - p)\mathbf{U}(s, T_1-).$$

A Stochastic Integral Equation

The limiting, scaled process:

$$d\mathbf{U}(s, t) = \mathbf{a}(\mathbf{U}(s, t))dt + \int_{\mathbf{M}} \mathbf{c}(\mathbf{U}(s, t), \mathbf{m}) \mathcal{P}[d\mathbf{m}, dt; \gamma]$$

- $\mathbf{c}(\mathbf{U}, d\mathbf{m})$ describes effect of catastrophes
- Poisson random measure \mathcal{P} describes arrival of catastrophes and their magnitudes, \mathbf{m} .
- Generalised Itô formula gives first passage times. (Gihman & Skorohod, 1972)

First Passage Times

First passage times, $\tau_G(\mathbf{U}_0)$, into a closed set $S \setminus G$ (i.e. out of G), starting from \mathbf{U}_0 , are a twice continuously differentiable solution, $g(\mathbf{U})$, to

$$(Lg)(\mathbf{U}) = -1, \mathbf{U} \in G$$

$$g(\mathbf{U}) = 0, \mathbf{U} \notin G,$$

- In the present case, $(Lh)(\mathbf{U})$ is given by

$$(Lh)(\mathbf{U}) = \nabla h(\mathbf{U}) \cdot \mathbf{a}(\mathbf{U}) - \gamma h(\mathbf{U}) + \gamma h((1-p)\mathbf{U}).$$

Solving First Passage Times

Slightly different conditions:

- $g(\mathbf{U})$ should be *continuous* along all trajectories $\mathbf{U}(s, t)$, and piecewise smooth along other smooth paths.
- $g(\mathbf{U})$ should be *bounded* for all \mathbf{U} .

Solve in ‘steps’: G_n is the region from which *at least* n catastrophes are needed to leave G .

Solving First Passage Times

The solution has the form

$$e^{-\gamma t} g(\mathbf{U}(s, t)) = - \int_0^t \gamma e^{-\gamma r} g((1-p)\mathbf{U}(s, r)) dr \\ - \gamma^{-1} [1 - e^{-\gamma t}] + C_1(s),$$

but we want a bounded solution, so set

$$C_1(s) = \int_0^\infty \gamma e^{-\gamma r} g((1-p)\mathbf{U}(s, r)) dr + \gamma^{-1}.$$

Solving First Passage Times

Hence (along trajectories that remain within G)

$$g(\mathbf{U}(s, t)) = \frac{1}{\gamma} + \left[\int_t^\infty \gamma e^{-\gamma r} g((1-p)\mathbf{U}(s, r)) dr \right] e^{\gamma t}.$$

Clearly, $C_1(s) = g(s, 0)$. We can also confirm:

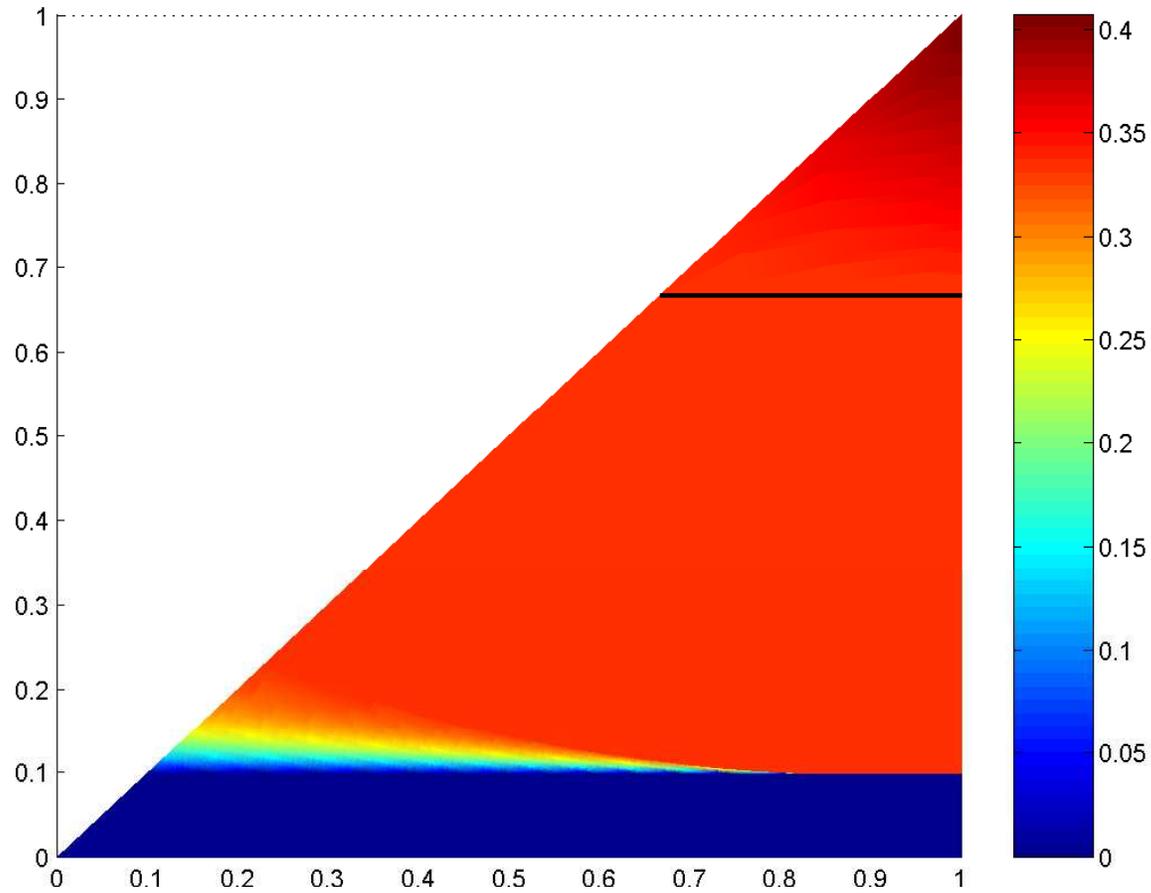
- if $G = G_1$, $g(\mathbf{U}) = \gamma^{-1}$ for all \mathbf{U} on trajectories remaining in G ;
- if $\mathbf{U}_\infty = \lim_{t \rightarrow \infty} \mathbf{U}(s, t)$ is in G , then $g(s, \infty-) = \gamma^{-1} + g((1-p)\mathbf{U}_\infty)$.

Solutions: A Special Case

If the fixed point is on the first 'step',

- $g(\mathbf{U}(s, t)) = \gamma^{-1}$, for all trajectories not leaving G_1 in finite time,
- solutions for trajectories heading out of G using the deterministic hitting time and a truncated exponential law, and
- the system of DEs $[\partial u / \partial t, \partial v / \partial t, \partial g / \partial t]$ gives first passage times for trajectories starting on higher steps.

Solutions: A Special Case



Solutions: General Case

The general case is a little more difficult.

- Define a mapping $K : H \rightarrow H$,

$$K(f(s, t)) := \frac{1}{\gamma} + e^{\gamma t} \int_t^{\infty} \gamma e^{-\gamma r} f((1-p)\mathbf{U}(s, r)) dr,$$

with H being the set of bounded functions $f : G \rightarrow \mathbb{R}_+$ under the condition

$$f(\mathbf{U}(s, t)) \geq \frac{1}{\gamma} + e^{\gamma t} \int_t^{\infty} \gamma e^{-\gamma r} f((1-p)\mathbf{U}(s, r)) dr.$$

Solutions: General Case

- $f \geq K(f)$, $f \in H$, so we might hope that the iterative application of K would lead to a fixed point, but...
- $H \neq \emptyset$ is equivalent to the existence of a solution, h , to

$$(Lh)(\mathbf{U}) \leq -1, \mathbf{U} \in G$$

$$h(\mathbf{U}) \geq 0, \mathbf{U} \notin G,$$

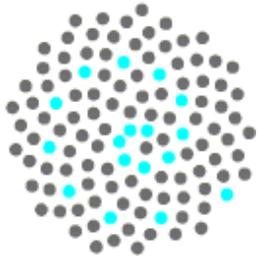
\equiv to a condition from Gihman & Skorohod for the existence of a solution $\tau_G \leq h$.

Solutions: General Case

- Is H empty? No! Hanson & Tuckwell (1981) analyse a similar 1D model for $u(s, t)$.
- In our 2D model, u does not depend on v , so:
 - (i) take $G' \supset G$ so that the first passage out of G' only depends on u ;
 - (ii) find $h(u) = \tau_{G'}(u)$;
 - (iii) then $h(u)$ satisfies the inequality condition for all v such that $(u, v) \in S$.

Thanks

- Phil Pollett and Hugh Possingham (advisors),
Chris Wilcox and Josh Ross.



AUSTRALIAN RESEARCH COUNCIL

Centre of Excellence for Mathematics
and Statistics of Complex Systems