Rare Event Simulation using Importance Sampling and Cross-Entropy

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Rare Event Simulation using Importance Sampling and Cross-Entropy - p. 1



Outline

- A rare event problem
- Stochastic SIS Logistic Epidemic (SIS)
- Crude Monte Carlo Method (CMCM)
- Importance Sampling (IS)
- Cross-Entropy Method (CE)
- Comparison of simulation estimates

A rare event problem

Denote X(t) as the size of the population at time t.

Let N denote the maximum population size.

We wish to estimate

 $\alpha = \mathbb{P}(X(t) \text{ hits 0 before N}).$

• Suppose $(X(t) : t \ge 0)$ is a birth-death process on finite space $\mathcal{X} = \{0, 1, \dots, N\}.$

$$(\bigcirc \begin{array}{c} \lambda_0 \\ \rightleftharpoons \\ \mu_1 \end{array}) (1) \begin{array}{c} \lambda_1 \\ \rightleftharpoons \\ \mu_2 \end{array}) (2) \begin{array}{c} \lambda_{N-2} \\ \cdots \\ \bigoplus \\ \mu_{N-1} \end{array}) (N-1) \begin{array}{c} \lambda_{N-1} \\ \rightleftharpoons \\ \mu_N \end{array}) (N)$$

Figure 1: Transition diagram of a finite-state birth-death process

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- Let $(X_m, m = 0, 1, ...)$ denote the corresponding jump chain.
- Let A be the collection of all the sample paths of (X_m) & let A₀ be the collection of all the paths that hit 0 before N.
- Let $X = (X_0, X_1, ...)$ be a random sample path of A and let A be the event $\{X \in A_0\}$.

Then we can write

$$\boldsymbol{x} = \mathbb{P}(A)$$
$$= \mathbb{E}_f H(\boldsymbol{X}) = \int_{\mathcal{A}} H(\boldsymbol{x}) f(\boldsymbol{x}; u, P) \mu(d\boldsymbol{x}).$$

where

 \bigcap

• H(X) is the indicator function of the rare event A defined by

$$H(oldsymbol{x}) = egin{cases} 1 & ext{if} \ oldsymbol{x} \in \mathcal{A}_0 \ 0 & ext{if} \ oldsymbol{x}
otin \mathcal{A}_0. \end{cases}$$

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- $u = (u(i) : i \in \mathcal{X})$ is the initial distribution.
- $P = (P(i, j) : i, j \in \mathcal{X})$ is the one-step transition matrix of (X_m) .

• The SIS model is a finite-state birth and death process for which the origin is an absorbing state.

$(0) \underset{\mu_1}{\leftarrow} (1) \underset{\mu_2}{\overset{\lambda_1}{\rightleftharpoons}} (2) \underset{\mu_{N-1}}{\overset{\lambda_{N-2}}{\longleftarrow}} (N-1) \underset{\mu_N}{\overset{\lambda_{N-1}}{\rightleftharpoons}} (N)$

Figure 2: Transition diagram of SIS model

- The SIS model is a finite-state birth and death process for which the origin is an absorbing state.
- The rate of infection per contact is denoted by λ and μ denotes the per-capita death rate.

$$(\bigcirc) \xleftarrow{\mu_1} (1) \xleftarrow{\lambda_1}{\mu_2} (2) \cdots \xleftarrow{\lambda_{N-2}}{\mu_{N-1}} (N-1) \xleftarrow{\lambda_{N-1}}{\mu_N} (N)$$

Figure 2: Transition diagram of SIS model

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The jump chain (X_m) has jump probabilities

$$p_i = \frac{\lambda(N-i)}{\mu N + \lambda(N-i)}$$

and $q_i = (1-p_i) = \frac{\mu N}{\mu N + \lambda(N-i)}$.

Crude Monte Carlo Method

We can estimate our probability using CMCM. This involves simulating n replicates, X^1, \ldots, X^n , from $f(\cdot; u, P)$ and setting

$$\hat{\alpha} = \frac{1}{n} \sum_{k=1}^{n} H(\boldsymbol{X}^{k}).$$

We simulate our model until the process hits N or 0. We count 1 if the process hits 0.

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The number of trials needed to get one successful trial has a geometric distribution with the expected value being 1/p, where p is the probability of a successful trial.

CMCM example

If we start in State 8 and we wish to estimate the probability of reaching 0 before 10, then we would require $1/\alpha$ runs to see one successful path hit 0 before 10. (Failure is hitting 10 before 0.)

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If we use CMCM, then we would require many more than 85,000 runs to obtain a reasonable estimate for α .

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The following conditions must also hold:

u(i) > 0 implies $\tilde{u}(i) > 0$ and P(i,j) > 0 implies $\tilde{P}(i,j) > 0$.

Under the alternative measure g we can estimate α by

$$\begin{aligned} \alpha &= \mathbb{E}_f H(\boldsymbol{X}) = \int_{\mathcal{A}} H(\boldsymbol{x}) \frac{f(\boldsymbol{x}; u, P)}{g(\boldsymbol{x}; \tilde{u}, \tilde{P})} g(\boldsymbol{x}; \tilde{u}, \tilde{P}) \mu(d\boldsymbol{x}) \\ &= \mathbb{E}_g \bigg(H(\boldsymbol{X}) L_T(\boldsymbol{X}; u, P, \tilde{u}, \tilde{P}); T < \infty \bigg), \end{aligned}$$

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where

$$L_m(\boldsymbol{x}; u, P, \tilde{u}, \tilde{P}) = \frac{f(\boldsymbol{x}; u, P)}{g(\boldsymbol{x}; \tilde{u}, \tilde{P})} = \frac{u(x_0) \prod_{k=0}^{m-1} P(x_k, x_{k+1})}{\tilde{u}(x_0) \prod_{k=0}^{m-1} \tilde{P}(x_k, x_{k+1})}.$$

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with $T = \inf\{m : X_m = 0 \text{ or } X_m = N\}$ ("Stopping Time")

Importance Sampling estimator

We can estimate α using the *importance sampling* (IS) estimator, defined by

$$\hat{\alpha} = \frac{1}{n} \sum_{i=1}^{n} H(\boldsymbol{X}) L_m(\boldsymbol{X}; u, P, \tilde{u}, \tilde{P}),$$

where (recall)

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The smallest variance is obtained when $g = g^*$, the *optimal importance sampling density*, given by

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If $H(\boldsymbol{x}) \geq 0$, then

$$g^*(\boldsymbol{x}) = \frac{H(\boldsymbol{x})f(\boldsymbol{x};u,P)}{\alpha}.$$

Cross-Entropy Method

The Kullback-Leibler Cross-Entropy (CE) measure defines a "distance" between two densities g and h

$$D(g,h) = \int g(\boldsymbol{x}) \ln \frac{g(\boldsymbol{x})}{h(\boldsymbol{x})} \mu(d\boldsymbol{x})$$

= $\int g(\boldsymbol{x}) \ln g(\boldsymbol{x}) \mu(d\boldsymbol{x}) - \int g(\boldsymbol{x}) \ln h(\boldsymbol{x}) \mu(d\boldsymbol{x}).$

The purpose of CE is to choose the IS density h such that the "distance" between the optimal IS density g^* and density h is as small as possible.

Properties of CE

1. $D(\cdot, \cdot)$ is non-symmetric ie: $D(g, h) \neq D(h, g)$, thus D(g, h) is not a true distance between g and h in a formal sense, although

2. $D(g,h) \ge 0$.

3. D(g,g) = 0.

Restrict the IS density

If we restrict the density to belong to some family \mathcal{F} which contains the original density

$$f(\mathbf{x}; u, P) = u(x_0) \prod_{k=0}^{m-1} P(x_k, x_{k+1})$$

and the alternative density

$$f(\boldsymbol{x}; \tilde{u}, \tilde{P}) = \tilde{u}(x_0) \prod_{k=0}^{m-1} \tilde{P}(x_k, x_{k+1})$$

CE optimisation problem

Then the CE method aims to solve the parametric optimisation problem

$$\min_{(\tilde{u},\tilde{P})} D(g^*, f(\,\cdot\,;\tilde{u},\tilde{P})),$$

where (recall)

$$g^*(\boldsymbol{x}) = \frac{H(\boldsymbol{x})f(\,\cdot\,;u,P\,)}{\alpha}.$$

Since $f(\cdot; u, P)$ does not depend on (\tilde{u}, \tilde{P}) , minimising the CE distance between g^* and $f(\cdot; \tilde{u}, \tilde{P})$ is equivalent to maximising, with respect to (\tilde{u}, \tilde{P}) ,

 $\int |H(\boldsymbol{x})| f(\boldsymbol{x}; u, P) \ln f(\boldsymbol{x}; \tilde{u}, \tilde{P}) \mu(d\boldsymbol{x})$ $= \mathbb{E}_{(u,P)} |H(\boldsymbol{X})| \ln f(\boldsymbol{X}; \tilde{u}, \tilde{P}).$

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Assuming $H(\mathbf{X}) \ge 0$, the optimal (\tilde{u}, \tilde{P}) (with respect to CE) is the solution to

 $(\tilde{u}^*, \tilde{P}^*) = \arg\max_{(\tilde{u}, \tilde{P})} \mathbb{E}_{(u, P)} H(\boldsymbol{X}) \ln f(\boldsymbol{X}; \tilde{u}, \tilde{P}).$

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Assuming $H(\mathbf{X}) \ge 0$, the optimal \tilde{P} (with respect to CE) is the solution to

$$\tilde{P}^* = \arg\max_{\tilde{P}} \mathbb{E}_{(u,P)} H(\boldsymbol{X}) \ln f(\boldsymbol{X}; u, \tilde{P}).$$

The optimal transition probability matrix is given by

$$\tilde{P}^*(i,j) = \frac{\mathbb{E}_{(u,P)}H(\boldsymbol{X})\sum_{k:X_k=i} 1_{(X_{k+1}=j)}}{\mathbb{E}_{(u,P)}H(\boldsymbol{X})\sum_{k:X_k=i} 1}.$$

We can approximate this optimal transition probability matrix by implementing IS to obtain:

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We can approximate this optimal transition probability matrix by implementing IS to obtain:

$$\tilde{P}_{l+1}^*(i,j) = \frac{\mathbb{E}_{(u,\tilde{P}_l)}H(\boldsymbol{X})L_m(\boldsymbol{X};u,P,u,\tilde{P}_l)\sum_{k:X_k=i}1_{(X_{k+1}=j)}}{\mathbb{E}_{(u,\tilde{P}_l)}H(\boldsymbol{X})L_m(\boldsymbol{X};u,P,u,\tilde{P}_l)\sum_{k:X_k=i}1}$$

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We can approximate this optimal transition probability matrix by implementing IS to obtain:

$$\tilde{P}_{l+1}^{*}(i,j) \approx \frac{\sum_{\boldsymbol{X}=\boldsymbol{X}^{1}}^{\boldsymbol{X}^{n}} H(\boldsymbol{X}) L_{m}(\boldsymbol{X}; u, P, u, \tilde{P}_{l}) \sum_{k:X_{k}=i} 1_{(X_{k+1}=j)}}{\sum_{\boldsymbol{X}=\boldsymbol{X}^{1}}^{\boldsymbol{X}^{n}} H(\boldsymbol{X}) L_{m}(\boldsymbol{X}; u, P, u, \tilde{P}_{l}) \sum_{k:X_{k}=i} 1},$$

Initial CE parameter

Original parameters:

$$p_i = \frac{\lambda(N-i)}{\mu N + \lambda(N-i)}$$
 and $q_i = (1-p_i) = \frac{\mu N}{\mu N + \lambda(N-i)}$.

Initial change of measures:

$$\tilde{p}_i = \frac{\mu(N-i)}{\lambda N + \mu(N-i)}$$
 and $\tilde{q}_i = (1-\tilde{p}_i) = \frac{\lambda N}{\lambda N + \mu(N-i)}$.



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Comparison of simulation estimates

$$N = 10, \lambda = 0.9, \mu = 0.1, \rho = 0.11, X_0 = 8,$$

No. of CE runs = 4

Sample Size	Exact	IS	CMCM
50	1.18E-05	1.40E-05	0
100	1.18E-05	1.64E-05	0
1000	1.18E-05	1.18E-05	0
2000	1.18E-05	1.18E-05	0

Comparison of CE runs

 $N = 10, \lambda = 0.9, \mu = 0.1, \rho = 0.11, X_0 = 8,$

Sample Size = 1000, Exact = 1.18E-05

CE run	IS	2 StD	\widetilde{p}_1	\widetilde{p}_5	\widetilde{p}_9
0	1.47E-05	3.21E-06	0.091	0.053	0.011
1	1.16E-05	1.79E-06	0.091	0.212	0
2	1.18E-05	4.12E-07	0.127	0.256	0
3	1.18E-05	1.38E-07	0.118	0.277	0
4	1.18E-05	9.09E-08	0.125	0.282	0
5	1.18E-05	5.89E-08	0.134	0.270	0

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