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$$1(i) \begin{vmatrix} -\lambda & \sqrt{3} \\ \sqrt{3} & -1-\lambda \end{vmatrix} = \lambda^2 - 4, \quad \lambda = \pm \sqrt{2}$$

$$(1-\lambda)a_1 + \sqrt{3}a_2 = 0 \quad \lambda=2 \Rightarrow \sqrt{3}a_2 = a_1,$$

$$\lambda=-2 \Rightarrow \sqrt{3}a_1 + \sqrt{3}a_2 = 0, \quad a_1=1, a_2 = -3/\sqrt{3} = -\sqrt{3}$$

$$\text{So } \tilde{x}_L(t) = c_1 e^{2t} \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 1 \\ -\sqrt{3} \end{bmatrix}$$

Particular solution $\tilde{x}_P(t) = u e^{2t} + v e^{-2t}$

$$\tilde{x}'_P = u e^{2t} - v e^{-2t} = \begin{bmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{bmatrix} (u e^{2t} + v e^{-2t}) + \begin{bmatrix} e^{2t} \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ \sqrt{3} e^{-2t} \end{bmatrix}$$

$$\begin{array}{l} \text{cfts} \\ e^{2t} \end{array}$$

$$\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad u_1 = -2/3, \quad u_2 = -\sqrt{3}/3$$

$$\begin{array}{l} \text{cfts} \\ e^{-2t} \end{array}$$

$$\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} 0 \\ \sqrt{3} \end{bmatrix} \quad v_1 = -1, \quad v_2 = 2\sqrt{3}/3$$

$$\tilde{x}(t) = \tilde{x}_L(t) + \tilde{x}_P(t)$$

$$= c_1 e^{2t} \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 1 \\ -\sqrt{3} \end{bmatrix} + \begin{bmatrix} -2/3 \\ -\sqrt{3}/3 \end{bmatrix} e^{2t} + \begin{bmatrix} -1 \\ 2\sqrt{3}/3 \end{bmatrix} e^{-2t}$$

$$5(b) \quad \tilde{x}' = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \tilde{x}, \quad \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$$

eigenvec eqn $-\lambda a_1 - a_2 = 0$ $\lambda = i, a_2 = -i a_1$ & an eigenvec is $\begin{bmatrix} 1 \\ -i \end{bmatrix}$, soln $\begin{bmatrix} 1 \\ -i \end{bmatrix} e^{it}$.That is $\begin{bmatrix} 1 \\ -i \end{bmatrix} (\cos t + i \sin t)$. The real & imaginary parts of this solution will give two REAL, LIN. INDEPT. solutions & there is no need to consider the other, complex conjugate solution.REAL PART $\tilde{x}^{(1)}(t) = \begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$; IMAG. PART $\tilde{x}^{(2)}(t) = \begin{bmatrix} \sin t \\ -\cos t \end{bmatrix}$

$$\tilde{x}(t) = c_1 \tilde{x}^{(1)}(t) + c_2 \tilde{x}^{(2)}(t) = \begin{cases} c_1 \cos t + c_2 \sin t \\ c_1 \sin t - c_2 \cos t \end{cases}$$

$$t=0, \quad 4=c_1, \quad c_2=0$$

$$\tilde{x}(t) = \begin{bmatrix} 4 \cos t \\ 4 \sin t \end{bmatrix}, \quad x^2 + y^2 = 16. \quad \text{circle, centre } (0,0), \quad \text{radius } 4.$$