# Estimating Extinction Risk in Population Models 

Phil Pollett

Department of Mathematics<br>The University of Queensland<br>http://www.maths.uq.edu.au/~pkp



Australian Research Council Centre of Excellence for Mathematics and Statistics of Complex Systems

## Collaborator

Joshua Ross<br>University of Adelaide

## Risk at UQ

## Phil Pollett

Mathematical modelling, stochastic process theory and applications: ecology, epidemiology, parasitology, telecommunications and chemical kinetics.

A current project: Estimating extinction risk in population models.


## Ross McVinish

Lévy processes and stochastic processes displaying long memory, Bayesian nonparametrics, computation for Bayesian statistics and time series analysis.

A current project: Statistical inference for partially observed population processes.


## PhD Projects

Robert Cope (July 2009 -)
Animal Movement Between Populations Deduced from Family Trees


Daniel Pagendam (March 2007-)
Experimental Design and Inference for Population Models


## Nimmy Thaliath (February 2009-)

Minimum Risk Optimal Portfolio Allocation: a Game Theoretic Approach


## Metapopulations

- A metapopulation is a population that is confined to a network of geographically separated habitat patches (for example a group of islands).
- Individual patches may suffer local extinction.
- Recolonization can occur through dispersal of individuals from other patches.


## A simple model

Suppose there are $N$ patches. Let $n(t)$ be the number occupied at time $t$ and suppose that $(n(t), t \geq 0)$ is a continuous-time Markov chain with transitions:

| Event | Transition | Rate |
| :--- | :--- | :--- |
| Colonisation | $n \rightarrow n+1$ | $\frac{c}{N} n(N-n)$ |
| Local extinction | $n \rightarrow n-1$ | en |

## A simple model

Suppose there are $N$ patches. Let $n(t)$ be the number occupied at time $t$ and suppose that $(n(t), t \geq 0)$ is a continuous-time Markov chain with transitions:

$$
\begin{array}{lll}
\text { Event } & \text { Transition } & \text { Rate } \\
\hline \text { Colonisation } & n \rightarrow n+1 & \frac{c}{N} n(N-n) \\
\text { Local extinction } & n \rightarrow n-1 & \text { en }
\end{array}
$$

This is the stochastic logistic (SL) model, though it has many names, having been rediscovered several times since Feller* proposed it.
*Feller, W. (1939) Die grundlagen der volterraschen theorie des kampfes ums dasein in wahrscheinlichkeitsteoretischer behandlung. Acta Biotheoretica 5, 11-40.


## A simple model

It is a stochastic analogue the classical Verhulst* population model (here, for the proportion of occupied patches): $x_{t}^{\prime}=c x_{t}\left(1-x_{t}\right)-e x_{t}=c x_{t}\left(1-\rho-x_{t}\right)$, where $\rho=e / c$, so that

$$
x_{t}=\frac{(1-\rho) x_{0}}{x_{0}+\left(1-\rho-x_{0}\right) e^{-(c-e) t}} .
$$

*Verhulst, P.F. (1838) Notice sur la loi que la population suit dans son accroisement. Corr. Math. et Phys. X, 113-121.

## A simple model

It is a stochastic analogue the classical Verhulst* population model (here, for the proportion of occupied patches): $x_{t}^{\prime}=c x_{t}\left(1-x_{t}\right)-e x_{t}=c x_{t}\left(1-\rho-x_{t}\right)$, where $\rho=e / c$, so that

$$
x_{t}=\frac{(1-\rho) x_{0}}{x_{0}+\left(1-\rho-x_{0}\right) e^{-(c-e) t}} .
$$

There are two equilibria: $x=0$ is stable if $c<e$, while $x=1-\rho(=1-e / c)$ is stable if $c>e$.
*Verhulst, P.F. (1838) Notice sur la loi que la population suit dans son accroisement. Corr. Math. et Phys. X, 113-121.

## The SL model $(c<e) x=0$ stable



## The SL model $(c>e) x=1-e / c$ stable

Simulation of SL Model ( $N=20, c=0.1625, e=0.0325$ )


## The SL model $(c>e) N$ large



## Spatially realistic models

The state of our Markov chain is now $\boldsymbol{n}=\left(n_{1}, \ldots, n_{N}\right)$, where $n_{i}=1$ if patch $i$ is occupied and $n_{i}=0$ if unoccupied. The transitions rates are:

## Event

Colonisation
Local extinction $\quad \boldsymbol{n} \rightarrow \boldsymbol{n}-\mathbf{1}_{i} \quad n_{i} \lambda_{i 0}$

Here $1_{i}$ is the unit vector with a 1 as its $i$-th entry, $\lambda_{j i}$ is the propagation rate from patch $j$ to patch $i$ and $\lambda_{i 0}$ is the local extinction rate.

## Spatially realistic models

$$
\begin{array}{lll}
\text { Event } & \text { Transition } & \text { Rate } \\
\hline \text { Colonisation } & \boldsymbol{n} \rightarrow \boldsymbol{n}+\mathbf{1}_{i} & \left(1-n_{i}\right) \sum_{j \neq i} n_{j} \lambda_{j i} \\
\text { Local extinction } & \boldsymbol{n} \rightarrow \boldsymbol{n}-\mathbf{1}_{i} & n_{i} \lambda_{i 0}
\end{array}
$$

For example, $\lambda_{i j}=g e^{-\beta \sqrt{d_{i j}}}$, where $g$ is the base propagation rate, $\beta$ is the exponential dispersion parameter and $d_{i j}$ is the distance between patches $i$ and $j$, and, $\lambda_{i 0}=\kappa / A_{i}$, where $A_{i}$ is the area of patch $i$; the rate of colonisation decreases with distance between patches, and the rate of local extinction decreases with patch area.

## Persistence times

## How do we evaluate the expected time to (total) extinction?

## Persistence times

How do we evaluate the expected time to (total) extinction?

Mangel and Tier's* Fact 2: "There is a simple and direct method for the computation of persistence times that virtually all biologists can use".
*Mangel, M. and Tier, C. (1994) Four facts every conservation biologist should know about persistence. Ecology 75, 607-614.


## Persistence times - my take on it

Theorem For a Markov chain with transition rates $Q=(q(m, n), m, n \in S)$, whose state space $S$ (possibly infinite) includes a subset $E$ which is reached with probability 1 , the expected time $\tau_{i}$ it takes to reach $E$ starting in state $i$ is the minimal non-negative solution to $\sum_{i \in S} q(i, j) \tau_{j}+1=0, i \notin E$, with $\tau_{i}=0$ for $i \in E$.

## For birth-death processes

For birth-death processes (such as the SL model) with birth rates $\left(a_{n}\right)$ and death rates $\left(b_{n}\right)$, the expected time $\tau_{i}(N)$ it takes to reach (the extinction state) 0 starting in state $i$ is given by

$$
\tau_{i}(N)=\sum_{j=1}^{i} \frac{1}{b_{j} \pi_{j}} \sum_{k=j}^{N} \pi_{k}, \quad \text { with } \tau_{0}(N)=0,
$$

where the "potential coefficients" $\left(\pi_{j}\right)$ are given by $\pi_{1}=1$ and $\pi_{j}=\prod_{k=2}^{j}\left(a_{k-1} / b_{k}\right)$ for $j \geq 2$.
(This formula is valid in the infinite state-space case, replacing $N$ by $\infty$.)

## For the SL model

For the SL model, the expected time to total extinction starting with $i$ patches occupied is given by

$$
\tau_{i}(N)=\frac{1}{e} \sum_{j=1}^{i} \sum_{k=0}^{N-j} \frac{1}{j+k} \prod_{l=0}^{k-1}\left(\frac{N-j-l}{N \rho}\right) .
$$

(Recall that $\rho=e / c$, where $c$ is the colonisation rate and $e$ is the local extinction rate.)
Whilst this admits further simplification, the form given reflects the algorithm one might use to evaluate $\tau_{i}(N)$, the product being evaluated recursively, and the sums evaluated in such a way as to minimize round-off error.

## For the SL model

This is far from being an explicit formula.

$$
\tau_{i}(N)=\frac{1}{e} \sum_{j=1}^{i} \sum_{k=0}^{N-j} \frac{1}{j+k} \prod_{l=0}^{k-1}\left(\frac{N-j-l}{N \rho}\right) .
$$

## For the SL model $(\rho<1)$

Note. $a_{N} \sim b_{N}$ here means $a_{N} / b_{N} \rightarrow 1$ as $N \rightarrow \infty$.
Theorem. If $\rho<1$, then

$$
\tau_{i}(N) \sim \frac{1-\rho^{i}}{c(1-\rho)^{2}}\left(\frac{e^{-(1-\rho)}}{\rho}\right)^{N} \sqrt{\frac{2 \pi}{N}} \quad \text { as } N \rightarrow \infty
$$

## The approximation


$\log _{10}$ of approximated expected time to extinction. The initial number of occupied patches is $n(0)=N / 5$ and $e=1$.

## The approximation



Relative error in the approximation. The initial number of occupied patches is $n(0)=N / 5$ and $e=1$.

## Bonus theorem: for the SL model $(\rho>1)$

Theorem. If $\rho>1$, then

$$
\tau_{1}(N) \rightarrow \frac{1}{c} \log \left(\frac{\rho}{\rho-1}\right)
$$

and, for $i \geq 2$,
$\tau_{i}(N) \rightarrow \frac{1}{c(\rho-1)}\left\{\left(\rho^{i}-1\right) \log \left(\frac{\rho}{\rho-1}\right)-\sum_{k=1}^{i-1} \frac{\left(\rho^{i-k}-1\right)}{k}\right\}$.

