# Modelling the long-term behaviour of population processes 

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Centre of Excellence for Mathematics and Statistics of Complex Systems

## The progress of an epidemic



## An autocatalytic reaction

Consider the reaction scheme $A \xrightarrow{X} B$, where $X$ is a catalyst. Suppose that there are two stages, namely

$$
A+X \xrightarrow{k_{1}} 2 X \quad \text { and } \quad 2 X \xrightarrow{k_{2}} B .
$$

Let $n_{t}$ be the number of $X$ molecules at time $t$.
Let $a$ be the number of $A$ molecules. Suppose that the concentration of $A$ is held constant.

The state space is $S=\{0,1,2, \ldots\}$ and the transitions are:

$$
\begin{array}{lll}
n \rightarrow n+1 & \text { at rate } & \frac{k_{1} a n}{V}=k_{1}[A] n \\
n \rightarrow n-2 & \text { at rate } & \frac{k_{2}}{V}\binom{n}{2} \quad(V \text { is volume })
\end{array}
$$

## An autocatalytic reaction



## A population network

There are $N$ "patches" of habitat. Each occupied patch becomes empty at rate $\mu$ and colonization of empty patches by occupied patches occurs at rate $\lambda / N$ for each suitable pair.
Let $n_{t}$ be the number of occupied patches at time $t$. The state space is $S=\{0,1, \ldots, N\}$ and the transitions are:

$$
\begin{array}{lll}
n \rightarrow n+1 & \text { at rate } & \frac{\lambda}{N} n(N-n) \\
n \rightarrow n-1 & \text { at rate } & \mu n
\end{array}
$$

I will call this model the stochastic logistic (SL) model, though it has many names, having been rediscovered several times since Feller* proposed it.
*Feller, W. (1939) Die grundlagen der volterraschen theorie des kampfes ums dasein in wahrscheinlichkeitsteoretischer behandlung. Acta Biotheoretica 5, 11-40.

## The SL model $(\lambda<\mu)$

Simulation of SL Model ( $N=20, \lambda=0.0325, \mu=0.1625$ )


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## Markov chains-ingredients

The state at time $t: n_{t} \in S$ (a countable set).
Transition rates $Q=\left(q_{n m}, n, m \in S\right): q_{n m}(\geq 0)$, for $m \neq n$, is the transition rate from state $n$ to state $m$ and $q_{n n}=-q_{n}$, where $q_{n}=\sum_{m \neq n} q_{n m}$, is the transition rate out of state $n$.

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Example. The autocatalytic reaction $A+X \xrightarrow{k_{1}} 2 X, 2 X \xrightarrow{k_{2}} B$

$$
\left.\begin{array}{c}
Q=\left(\begin{array}{cccccc}
0 & 0 & 0 & 0 & 0 & \ldots \\
0 & -\frac{k_{1}}{V} a & \frac{k_{1}}{V} a & 0 & 0 & \ldots \\
\frac{k_{2}}{V} & 0 & -\frac{1}{V}\left(2 k_{1} a+k_{2}\right) & 2 \frac{k_{1}}{V} a & 0 & \ldots \\
0 & 3 \frac{k_{2}}{V} & 0 & -\frac{3}{V}\left(k_{1} a+k_{2}\right) & 3 \frac{k_{1}}{V} a & \ldots \\
\vdots & \vdots & \vdots & \vdots & \vdots & \ddots
\end{array}\right) \\
\left(n \rightarrow n+1 \text { at rate } \frac{k_{1}}{V} a n \quad\right. \text { and } \\
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## More ingredients

Assumptions: take 0 to be the sole absorbing state (that is, $q_{0 n}=0$ ). For simplicity, suppose that $C=S-\{0\}$ is "irreducible" and that we reach 0 from $C$ with probability 1.
State probabilities: $\mathbf{p}(t)=\left(p_{n}(t), n \in S\right), p_{n}(t)=\operatorname{Pr}\left(n_{t}=n\right)$.
Initial distribution: $\mathbf{p}(0)=\mathbf{a}=\left(a_{n}, n \in S\right)\left(a_{0}=0\right)$.
Forward equations (FEs): the state probabilities satisfy

$$
\mathbf{p}^{\prime}(t)=\mathbf{p}(t) Q, \quad \mathbf{p}(0)=\mathbf{a} .
$$

In particular, since $q_{0 n}=0$,

$$
p_{n}^{\prime}(t)=\sum_{m \in C} p_{m}(t) q_{m n} \quad(n \in S, t>0)
$$

Or, written as a master equation:

$$
p_{n}^{\prime}(t)=\sum_{m \in C}\left\{p_{m}(t) q_{m n}-p_{n}(t) q_{n m}\right\} \quad(n \in S, t>0) .
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## Solution to FEs?

If $S$ is a finite set (or, more generally, if $\sup _{n} q_{n}<\infty$ ), then the forward equations $\mathbf{p}^{\prime}(t)=\mathbf{p}(t) Q$, with $\mathbf{p}(0)=\mathbf{a}$, have the unique solution $\mathbf{p}(t)=\mathbf{a} \exp (Q t), t \geq 0$, where $\exp$ is the matrix exponential:

$$
\exp (A)=I+A+\frac{A^{2}}{2!}+\cdots+\frac{A^{n}}{n!}+\ldots
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Use Matlab's expm or, better (especially if $Q$ is sparse), Roger Sidje's expokit: www.maths.uq.edu.au/expokit/

## The SL model $(\lambda>\mu)$



## Exercise 1

Suppose that at any given time during your office hours there are $n$ students waiting with probability $p_{n}:=(1-p) p^{n}$ where say $p=0.1$, so that, for example, the chance that there are no students waiting is $p_{0}=1-p=0.9$.

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There is a knock at the door. What is the probability that there are $n$ students waiting?

Answer: $p_{n} /\left(1-p_{0}\right)=(1-p) p^{n-1}=(0.9) \times(0.1)^{n-1}(n \geq 1)$.

## Modelling quasi stationarity

Recall that $S=\{0\} \cup C$, where 0 is an absorbing state and $C$ is the set of transient states.

Define conditional state probabilities $\mathbf{r}(t)=\left(r_{n}(t), n \in C\right)$ by

$$
r_{n}(t)=\operatorname{Pr}\left(n_{t}=n \mid n_{t} \in C\right),
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the chance of being in state $n$ given that the process has not reached 0 .

## Conditional state probabilities



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Does $\mathbf{r}(t) \rightarrow \mathbf{r}$ as $t \rightarrow \infty$ ?
Definition. A distribution $\mathbf{r}=\left(r_{n}, n \in C\right)$ satisfying $\mathbf{r}(t)=\mathbf{r}$ for all $t>0$ is called a quasi-stationary distribution (QSD). If $\mathbf{r}(t) \rightarrow \mathbf{r}$ then $\mathbf{r}$ is a limiting-conditional distribution (LCD).

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So, we may think of a QSD as being an equilibrium point r of the master equation governing the evolution of the conditional state probabilities $\mathbf{r}(t)=\left(r_{n}(t), n \in C\right)$, where recall that

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And, if r is asymptotically stable, then r is an LCD.

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And, if $\mathbf{r}$ is asymptotically stable, then $\mathbf{r}$ is an LCD.
So, what is the master equation for $\mathbf{r}(t)$ ?

## Some calculations

For $n \in C$,

$$
\begin{aligned}
r_{n}(t) & =\operatorname{Pr}\left(n_{t}=n \mid n_{t} \in C\right) \\
& =\frac{\operatorname{Pr}\left(n_{t}=n\right)}{\operatorname{Pr}\left(n_{t} \in C\right)}=\frac{p_{n}(t)}{\sum_{m \in C} p_{m}(t)}=\frac{p_{n}(t)}{1-p_{0}(t)} .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
r_{n}^{\prime}(t) & =\frac{p_{n}^{\prime}(t)}{1-p_{0}(t)}+p_{n}(t) \frac{p_{0}^{\prime}(t)}{\left(1-p_{0}(t)\right)^{2}} \\
& =\frac{p_{n}^{\prime}(t)}{1-p_{0}(t)}+r_{n}(t) \frac{p_{0}^{\prime}(t)}{1-p_{0}(t)} \quad\left(\text { now use FEs for } p_{n}(t)\right) \\
& =\sum_{m \in C} r_{m}(t) q_{m n}+r_{n}(t) \sum_{m \in C} r_{m}(t) q_{m 0} .
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$$

## Modelling quasi stationarity

We arrive at

$$
r_{n}^{\prime}(t)=\sum_{m \in C} r_{m}(t) q_{m n}+r_{n}(t) \sum_{m \in C} r_{m}(t) q_{m 0}
$$

Since $\sum_{n \in S} q_{m n}=0$, this can be written

$$
\mathbf{r}^{\prime}(t)=\mathbf{r}(t) Q_{C}-\nu(t) \mathbf{r}(t)
$$

where $\nu(t)=\mathbf{r}(t) Q_{C} \mathbf{1}$, and $Q_{C}$ is the restriction of $Q$ to $C$.

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where $\nu(t)=\mathbf{r}(t) Q_{C} \mathbf{1}$, and $Q_{C}$ is the restriction of $Q$ to $C$.
Formally we have $\mathbf{r}(t) \rightarrow \mathbf{r}$, where $\mathbf{r}$ satisfies

$$
\mathbf{r} Q_{C}=\nu \mathbf{r}
$$

so that $\mathbf{r}=\left(r_{n}, n \in C\right)$ is a left eigenvector of $Q_{C}$ corresponding to a (strictly negative) real eigenvalue $\nu$. Postmultiplying by 1 gives $\nu=\mathbf{r} Q_{C} \mathbf{1}$, or, written out, $\nu=-\sum_{n \in C} r_{n} q_{n 0}$.

## Modelling quasi stationarity

If the state space is finite, this can be justified using classical Perron-Frobenius theory.

Theorem The restriction $Q_{C}$ of $Q$ to $C$ has eigenvalues with strictly negative real parts and the one with maximal real part (called $\nu$ above) is real and has multiplicity 1 , and, the corresponding left eigenvector $\mathbf{x}=\left(x_{n}, n \in C\right)$ has strictly positive entries.
The quasi-stationary distribution $\mathbf{r}=\left(r_{n}, n \in C\right)$ exists uniquely and is given by $r_{n}=x_{n} / \sum_{m \in C} x_{m}$. Moreover, $\mathbf{r}$ is the limiting-conditional distribution. In particular, if $\operatorname{Pr}\left(n_{0} \in C\right)=1$,

$$
\operatorname{Pr}\left(n_{t}=n \mid n_{t} \in C\right) \rightarrow r_{n} \quad \text { as } \quad t \rightarrow \infty
$$

the limit being the same for all initial distributions.

## QSD of the SL model



## QSD of the SL model

Simulation of SL Model (with QSD shown) $(N=20, \lambda=0.1625, \mu=0.0325)$


## Proportion of patches occupied



## The SL model $(N=20)$

Simulation of SL Model ( $N=20, \lambda=0.1625, \mu=0.0325$ )


## The SL model $(N=50)$



## The SL model $(N=100)$

Simulation of SL Model ( $N=100, \lambda=0.1625, \mu=0.0325$ )


## The SL model $(N=200)$

Simulation of SL Model ( $N=200, \lambda=0.1625, \mu=0.0325$ )


## The SL model $(N=500)$



## The SL model $(N=1000)$



## The SL model ( $N=10000$ )



## Density dependence

The idea is the same as for deterministic models: the rate of change of $n_{t}$ depends on $n_{t}$ only through the "density" $n_{t} / N$ :

$$
n \rightarrow n+l \quad \text { at rate } \quad N f_{l}\left(\frac{n}{N}\right) \quad(l \neq 0)
$$

for suitable functions $f_{l}(x)$.
The analogous (approximating!) deterministic model for the "density" $x_{t}:=n_{t} / N$ is

$$
\frac{d x}{d t}=F(x):=\sum_{l \neq 0} l f_{l}(x) .
$$

## The SL model

For the SL model we have $S=\{0,1, \ldots, N\}$ and transitions:

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\begin{aligned}
n \rightarrow n+1 & \text { at rate } & \frac{\lambda}{N} n(N-n) & =N \lambda \frac{n}{N}\left(1-\frac{n}{N}\right) \\
n \rightarrow n-1 & \text { at rate } & \mu n & =N \mu \frac{n}{N}
\end{aligned}
$$

Therefore, $f_{+1}(x)=\lambda x(1-x)$ and $f_{-1}(x)=\mu x, x \in E:=[0,1]$, and so $F(x)=\lambda x(q-x), x \in E$, where $q=1-\mu / \lambda$.

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We arrive at the classical Verhulst (1838) model $x_{t}^{\prime}=\lambda x_{t}\left(q-x_{t}\right)$, which for us describes the proportion of occupied patches. It has the unique solution

$$
x_{t}=\frac{q x_{0}}{x_{0}+\left(q-x_{0}\right) e^{-(\lambda-\mu) t}} \quad(t \geq 0) .
$$

## The SL model $(\lambda<\mu)$

Simulation of SL Model ( $N=20, \lambda=0.0325, \mu=0.1625$ )


## The SL model $(\lambda>\mu)$

Simulation of SL Model ( $N=20, \lambda=0.1625, \mu=0.0325$ )


## The SL model $(N=1000)$



## Density dependence of MCs

Let $\left(n_{t}, t \geq 0\right)$ be a continuous-time Markov chain taking values in $S \subseteq \mathrm{Z}^{k}$ with transition rates $Q=\left(q_{n m}, n, m \in S\right)$.

We identify a quantity $N$, usually related to the size of the system being modelled (for example, volume, area, number of patches, population ceiling).

Definition (Kurtz*) The model is density dependent if there is a subset $E$ of $\mathrm{R}^{k}$ and a continuous function $f: \mathrm{Z}^{k} \times E \rightarrow \mathrm{R}$, such that

$$
q_{n, n+l}=N f_{l}\left(\frac{n}{N}\right), \quad l \neq 0 \quad\left(l \in \mathrm{Z}^{k}\right) .
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## Density dependence of MCs

We now formally define the density process $\left(X_{t}^{(N)}\right)$ by

$$
X_{t}^{(N)}=n_{t} / N \quad(t \geq 0)
$$

This is a Markov chain that takes values in the lattice $S_{N}:=S / N$ and has transition rates $q_{x, x+l / N}, x \in S_{N}, l \in \mathrm{Z}^{k}$.
We hope that $\left(X_{t}^{(N)}\right)$ becomes more deterministic as $N$ gets large. Moreover, we anticipate that the limiting deterministic trajectory satisfies $x_{t}^{\prime}=F\left(x_{t}\right)$, where

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To simplify the statement of results, I'm going to assume that the state space is finite.

## A law of large numbers

The following functional law of large numbers establishes convergence of the family $\left(X_{t}^{(N)}\right)$ to the unique trajectory of the appropriate approximating deterministic model.

Theorem (Kurtz*) Suppose $F$ is Lipschitz on $E$ (that is, $\left.|F(x)-F(y)|<M_{E}|x-y|\right)$. If $\lim _{N \rightarrow \infty} X_{0}^{(N)}=x_{0}$, then the density process $\left(X_{t}^{(N)}\right)$ converges uniformly in probability on $[0, t]$ to $\left(x_{t}\right)$, the unique (deterministic) trajectory satisfying

$$
\frac{d}{d s} x_{s}=F\left(x_{s}\right) \quad\left(x_{s} \in E, s \in[0, t]\right) .
$$

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## A law of large numbers

Convergence uniformly in probability on $[0, t]$ means that for every $\epsilon>0$,

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$$

The conditions of the theorem hold for the SL model: since $F(x)=\lambda x(q-x)$, we have, for all $x, y \in E=[0,1]$, that

$$
|F(x)-F(y)|=\lambda|x-y||q-(x+y)| \leq(2-q) \lambda|x-y| .
$$

So, provided $X_{0}^{(N)} \rightarrow x_{0}$ as $N \rightarrow \infty$, the proportion $\left(X_{t}^{(N)}\right)$ of occupied patches converges (uniformly in probability on finite time intervals) to deterministic trajectories in $E$ :

$$
x_{t}=\frac{q x_{0}}{x_{0}+\left(q-x_{0}\right) e^{-(\lambda-\mu) t}} \quad\left(x_{0} \in E, t \geq 0\right)
$$

## The SL model $(N=50)$



## Variation in SL model



## Variation in SL model



## Variation in SL model



## Variation in SL model



## Modelling variation

We will consider the family of processes $\left\{\left(Z_{t}^{(N)}\right)\right\}$, indexed by $N$, and defined by

$$
Z_{t}^{(N)}=\sqrt{N}\left(X_{t}^{(N)}-x_{t}\right) \quad(t \geq 0)
$$

where recall that $\left(X_{t}^{(N)}\right)$ is the density process, defined by $X_{t}^{(N)}=n_{t} / N$, and $\left(x_{t}\right)$ is the limiting deterministic trajectory, which satisfies $x_{t}^{\prime}=F\left(x_{t}\right)$, where

$$
F(x)=\sum_{l \neq 0} l f_{l}(x) \quad(x \in E)
$$

I will call $\left\{\left(Z_{t}^{(N)}\right)\right\}$ the scaled density process.

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I will call $\left\{\left(Z_{t}^{(N)}\right)\right\}$ the scaled density process.
In view of the Central Limit Theorem we might expect $\left\{\left(Z_{t}^{(N)}\right)\right\}$ to become more "Gaussian" as $N$ gets large; in particular, for each fixed $t, Z_{t}^{(N)} \xrightarrow{D} \operatorname{Normal}\left(\mu_{t}, V_{t}\right)$ as $N \rightarrow \infty$.

## The SL model $(N=20)$

Simulation of SL Model ( $N=20, \lambda=0.1625, \mu=0.0325$ )


## The SL model $(N=50)$



## The SL model $(N=100)$



## The SL model $(N=200)$



## The SL model $(N=500)$



## The SL model $(N=1000)$



## The SL model ( $N=10000$ )



## Kurtz's theorem

In a later paper Kurtz* proved a functional central limit law which establishes that, for large $N$, the fluctuations about the deterministic trajectory do indeed follow a Gaussian diffusion, provided that some mild extra conditions are satisfied.
*Kurtz, T. (1971) Limit theorems for sequences of jump Markov processes approximating ordinary differential processes. J. Appl. Probab. 8, 344-356.

## A central limit law

Theorem (Kurtz) Suppose that $F$ is Lipschitz and has uniformly continuous first derivative on $E$, and that the $k \times k$ matrix $G(x)$ defined by $G_{i j}(x)=\sum_{l \neq 0} l_{i} l_{j} f_{l}(x)$, for each $x \in E$, is uniformly continuous on $E$.

Let $\left(x_{t}\right)$ be the unique deterministic trajectory starting at $x_{0}$ and suppose that $\lim _{N \rightarrow \infty} \sqrt{N}\left(X_{0}^{(N)}-x_{0}\right)=z$.

Then, $\left\{\left(Z_{t}^{(N)}\right)\right\}$ converges weakly in $D[0, t]$ (the space of right-continuous, left-hand limits functions on $[0, t]$ ) to a Gaussian diffusion $\left(Z_{t}\right)$ with initial value $Z_{0}=z$ and with mean and covariance given by $\mu_{s}:=\mathbb{E}\left(Z_{s}\right)=M_{s} z$, where

$$
\begin{aligned}
& M_{s}=\exp \left(\int_{0}^{s} B_{u} d u\right) \text { and } B_{s}=\nabla F\left(x_{s}\right), \text { and } \\
& \qquad V_{s}:=\operatorname{Cov}\left(Z_{s}\right)=M_{s}\left(\int_{0}^{s} M_{u}^{-1} G\left(x_{u}\right)\left(M_{u}^{-1}\right)^{T} d u\right) M_{s}^{T} .
\end{aligned}
$$

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$$

## The SL model

For the SL model we have $F(x)=\lambda x(q-x)$, and the solution to $d x / d t=F(x)$ is

$$
x(t)=\frac{q x_{0}}{x_{0}+\left(q-x_{0}\right) e^{-(\lambda-\mu) t}} .
$$

We also have $F^{\prime}(x)=\lambda(q-2 x)$ and

$$
G(x)=\sum_{l} l^{2} f_{l}(x)=\lambda x(2-q-x)=F(x)+2 \mu x
$$

giving

$$
M_{t}=\exp \left(\int_{0}^{t} F^{\prime}\left(x_{s}\right) d s\right)=\frac{q^{2} e^{-(\lambda-\mu) t}}{\left(x_{0}+\left(q-x_{0}\right) e^{-(\lambda-\mu) t}\right)^{2}} .
$$

We can evaluate

$$
V_{t}:=\operatorname{Var}\left(Z_{t}\right)=M_{t}^{2}\left(\int_{0}^{t} G\left(x_{s}\right) / M_{s}^{2} d s\right)
$$

numerically, or ...

## Or

$$
\begin{aligned}
& V_{t}=x_{0}\left((1+q) x_{0}^{3}+x_{0}^{2}(6+5 q)\left(q-x_{0}\right) e^{-\alpha t}\right. \\
& \quad+2 x_{0}(3+2 q)\left(q-x_{0}\right)^{2} \alpha t e^{-2 \alpha t} \\
& \quad-\left(\left(q-x_{0}\right)\left[3(1+q) x_{0}^{2}+(3+q) q x_{0}-(3+2 q) q^{2}\right]\right. \\
& \left.\quad+(1+q) q^{3}\right) e^{-2 \alpha t} \\
& \left.\quad-(2+q)\left(q-x_{0}\right)^{3} e^{-3 \alpha t}\right) /\left(x_{0}+\left(q-x_{0}\right) e^{-\alpha t}\right)^{4}
\end{aligned}
$$

where $\alpha=\lambda-\mu$.

## The SL model



Deterministic trajectory plus or minus two standard deviations

## The SL model



Deterministic trajectory plus or minus two standard deviations (Empirical variance in blue and diffusion approximation in green)

## Scaled density process



## Equilibrium phase



## Equilibrium phase



## Equilibrium phase



## Equilibrium

If we are only interested in the equilibrium phase of the process, then it is simpler to consider the family of processes $\left\{\left(Z_{t}^{(N)}\right)\right\}$ defined by $Z_{t}^{(N)}=\sqrt{N}\left(X_{t}^{(N)}-x_{\mathrm{eq}}\right)$, where $x_{\mathrm{eq}}$ is an equilibrium point of the deterministic model. We can now be far more precise about the approximating diffusion.
Corollary If $x_{\text {eq }}$ satisfies $F\left(x_{\text {eq }}\right)=0$, then, under the conditions of the theorem, $\left\{\left(Z_{t}^{(N)}\right)\right\}$ converges weakly in $D[0, t]$ to an Ornstein-Uhlenbeck (OU) process $\left(Z_{t}\right)$ with initial value $Z_{0}=z$, local drift matrix $B:=\nabla F\left(x_{\mathrm{eq}}\right)$ and local covariance matrix $G\left(x_{\mathrm{eq}}\right)$. In particular, $Z_{s}$ is normally distributed with mean and covariance given by $\mu_{s}:=\mathbb{E}\left(Z_{s}\right)=e^{B s} z$ and

$$
V_{s}:=\operatorname{Cov}\left(Z_{s}\right)=\int_{0}^{s} e^{B u} G\left(x_{\mathrm{eq}}\right) e^{B^{T} u} d u .
$$

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$$

## The OU approximation

Note that

$$
V_{s}=\int_{0}^{s} e^{B u} G\left(x_{\mathrm{eq}}\right) e^{B^{T} u} d u=V_{\mathrm{st}}-e^{B s} V_{\mathrm{st}} e^{B^{T} s},
$$

where $V_{\mathrm{st}}$, the stationary covariance matrix, satisfies

$$
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For the SL model,

$$
\operatorname{Var}\left(X_{t}^{(N)}\right) \simeq \frac{1}{N}\left(\frac{\mu}{\lambda}\right)\left(1-e^{-2(\lambda-\mu) t}\right) \quad\left(\simeq \frac{\mu}{N \lambda} \text { for large } t\right) .
$$

## The SL model



Deterministic equilibrium plus or minus two standard deviations (Deterministic trajectory in red and OU approximation in green)

## An epidemic model



## An epidemic model

The state at time $t$ is $\left(s_{t}, i_{t}\right)$, where $s_{t}$ is the number of susceptibles and $i_{t}$ is the number of infectives.
The state space is $S=\{(s, i): s, i=0,1,2, \ldots\}$.
The transitions are:

$$
\begin{array}{llll}
(s, i) \rightarrow(s+1, i) & \text { at rate } & \alpha & (\rightarrow \text { immigration }) \\
(s, i) \rightarrow(s, i-1) & \text { at rate } & \gamma i & (\downarrow \text { death or removal }) \\
(s, i) \rightarrow(s-1, i+1) & \text { at rate } & \frac{\beta}{N} s i & (\nwarrow \text { infection }) \\
& & & (N \text { is system size })
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\end{array}
$$

Is the model density dependent?

## An epidemic model

Is the Markov chain density dependent?

$$
\begin{array}{lll}
(s, i) \rightarrow(s+1, i) & \text { at rate } & N\left(\frac{\alpha}{N}\right) \\
(s, i) \rightarrow(s, i-1) & \text { at rate } & N \gamma\left(\frac{i}{N}\right) \\
(s, i) \rightarrow(s-1, i+1) & \text { at rate } & N \beta\left(\frac{s}{N}\right)\left(\frac{i}{N}\right)
\end{array}
$$

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The $\alpha / N$ term is a problem. Since $\alpha$ is a constant, the immigration term will vanish when $N$ becomes large.

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\end{array}
$$

The $\alpha / N$ term is a problem. Since $\alpha$ is a constant, the immigration term will vanish when $N$ becomes large.
For density dependence we must have $\alpha=O(N)$ (say $\alpha \sim a N)$. Is this reasonable?

## An epidemic model

$$
\begin{array}{lll}
(s, i) \rightarrow(s, i)+(+1,0) & \text { at rate } & N\left(\frac{\alpha}{N}\right) \\
(s, i) \rightarrow(s, i)+(0,-1) & \text { at rate } & N \gamma\left(\frac{i}{N}\right) \\
(s, i) \rightarrow(s, i)+(-1,+1) & \text { at rate } & N \beta\left(\frac{s}{N}\right)\left(\frac{i}{N}\right)
\end{array}
$$

## An epidemic model

$$
\begin{aligned}
& (s, i) \rightarrow(s, i)+(+1,0) \quad \text { at rate } \quad N\left(\frac{\alpha}{N}\right) \\
& (s, i) \rightarrow(s, i)+(0,-1) \quad \text { at rate } \quad N \gamma\left(\frac{i}{N}\right) \\
& (s, i) \rightarrow(s, i)+(-1,+1) \quad \text { at rate } \quad N \beta\left(\frac{s}{N}\right)\left(\frac{i}{N}\right) \\
& f_{(+1,0)}(\mathbf{x})=a \quad f_{(0,-1)}(\mathbf{x})=\gamma x_{2} \quad f_{(-1,+1)}(\mathbf{x})=\beta x_{1} x_{2} \\
& F(\mathbf{x})=\sum_{l \neq 0} l f_{l}(\mathbf{x})=\binom{a-\beta x_{1} x_{2}}{-\gamma x_{2}+\beta x_{1} x_{2}} \quad \mathbf{x}=\binom{x_{1}}{x_{2}}
\end{aligned}
$$

(The deterministic model is $\mathrm{x}_{t}^{\prime}=F(\mathbf{x})$ )

## An epidemic model



## An epidemic model



## An epidemic model

$F\left(\mathrm{x}_{\mathrm{eq}}\right)=0$ gives $\mathrm{x}_{\mathrm{eq}}=(\gamma / \beta, a / \gamma)$. Also,

$$
\nabla F(\mathbf{x})=\left(\begin{array}{cc}
-\beta x_{2} & -\beta x_{1} \\
\beta x_{2} & \beta x_{1}-\gamma
\end{array}\right) \quad B:=\nabla F\left(\mathbf{x}_{\mathrm{eq}}\right)=\left(\begin{array}{cc}
-a \beta / \gamma & -\gamma \\
a \beta / \gamma & 0
\end{array}\right)
$$

The eigenvalues of $B$ are both negative if $4 \gamma^{2} \leq a \beta$, and complex if $4 \gamma^{2}>a \beta$.

$$
G_{i j}(\mathbf{x})=\sum_{l \neq 0} l_{i} l_{j} f_{l}(\mathbf{x}) .
$$

So,

$$
G(\mathbf{x})=\left(\begin{array}{cc}
a+\beta x_{1} x_{2} & -\beta x_{1} x_{2} \\
-\beta x_{1} x_{2} & \gamma x_{2}+\beta x_{1} x_{2}
\end{array}\right) .
$$

## An epidemic model

$$
\begin{gathered}
B=\left(\begin{array}{cc}
-a \beta / \gamma & -\gamma \\
a \beta / \gamma & 0
\end{array}\right) \\
G\left(\mathbf{x}_{\mathrm{eq}}\right)=\left(\begin{array}{cc}
2 a & -a \\
-a & 2 a
\end{array}\right) \\
V_{t}:=\operatorname{Cov}\left(Z_{t}\right)=V_{\mathrm{st}}-e^{B t} V_{\mathrm{st}} e^{B^{T} t} \\
V_{\mathrm{st}}=\left(\begin{array}{cc}
\frac{\gamma}{\beta}\left(1+\frac{\gamma^{2}}{a \beta}\right) & -\frac{\gamma}{\beta} \\
-\frac{\gamma}{\beta} & \frac{\gamma}{\beta}+\frac{a}{\gamma}
\end{array}\right)
\end{gathered}
$$

## The OU approximation



## Van Kampen's method

Van Kampen* considered the "Kramers-Moyal expansion" of the master equation (aka the forward equation) for the jump process $\left(n_{t}\right)$. He transformed $n_{t}$ by introducing a new variable $Z_{t}$ so that $n_{t}=N x_{t}+\sqrt{N} Z_{t}$.
He then derived the corresponding master equation for $\left(Z_{t}\right)$, noting that if $\left(x_{t}\right)$ obeys $x_{t}^{\prime}=F\left(x_{t}\right)$, then terms of order $N^{1 / 2}$ cancel, and only a single term in the expansion survives in the limit as $N \rightarrow \infty$ : arriving at the Fokker-Planck equation

$$
\frac{\partial}{\partial t} P_{z}(t)=-\alpha\left(x_{t}\right) z \frac{\partial}{\partial z} P_{z}(t)+\frac{1}{2} \beta\left(x_{t}\right) \frac{\partial^{2}}{\partial^{2} z} P_{z}(t)
$$

where $\alpha(\cdot)$ and $\beta(\cdot)$ are determined for the particular model. So, the variable $Z_{t}$ is indeed Gaussian.
*Van Kampen, N.G. (1961) A Power series expansion of the master equation. Canadian J. Phys. 39, 551-567.

