

Population networks with no occupancy ceiling

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ANZIAM Annual Conference 2021

Virtual, 31 January- 5 February 2021



This is joint work with ...

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The basic model

An *infinite occupancy process* $\mathbf{X}_t = (X_{i,t})_{i=1}^{\infty}$ is a (time-homogeneous) Markov chain on $\{0, 1\}^{\mathbb{Z}^+}$ with the property that, conditional on \mathbf{X}_t , the occupancies $X_{1,t+1}, X_{2,t+1}, \dots$, at time $t + 1$, are mutually independent. In particular, the dynamics are determined by the collection of functions

$$P_i(\mathbf{x}) = \mathbb{P}(X_{i,t+1} = 1 | \mathbf{X}_t = \mathbf{x}), \quad i = 1, 2, \dots$$



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It will be convenient to write

$$P_i(\mathbf{x}) = S_i(\mathbf{x})x_i + C_i(\mathbf{x})(1 - x_i), \quad \mathbf{x} \in \{0, 1\}^{\mathbb{Z}^+},$$

where $S_i, C_i : \{0, 1\}^{\mathbb{Z}^+} \rightarrow [0, 1]$; $C_i(\mathbf{x})$ and $1 - S_i(\mathbf{x})$ are the (configuration dependent) “flip” probabilities.

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Voter Model: $S_i(\mathbf{x}) = 1 - \sum_{j=1}^{\infty} p_{ij}(1 - x_j)$, $C_i(\mathbf{x}) = \sum_{j=1}^{\infty} p_{ij}x_j$ ($p_{ii} = 0$).

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Domany-Kinzel PCA on the discrete torus of length n : $S_i(\mathbf{x}) = (q_2 - q_1)x_{i+1}$, $C_i(\mathbf{x}) = q_1x_{i+1}$, $q_1, q_2 \in [0, 1]$.



A metapopulation model

The sites $i = 1, 2, \dots$ are habitat patches, and $X_{i,t}$ is 1 or 0 according to whether patch i is occupied or unoccupied at time t . $S_i(\mathbf{x}) = s_i$ (patch i *survival probability*) is the same for all \mathbf{x} , and

$$C_i(\mathbf{x}) = f \left(a_i \sum_{j=1}^{\infty} d_{ij} X_j \right),$$

where $f : [0, \infty) \rightarrow [0, 1]$ (called the *colonisation function*) satisfies $f(0) = 0$ (so there is total extinction at $\mathbf{x} \equiv 0$), and is typically an increasing function, a_i is a weight that may be interpreted as the capacity, or area, of patch i , and d_{ij} is the migration potential from patch j to patch i . (Further assumptions will be added later.)

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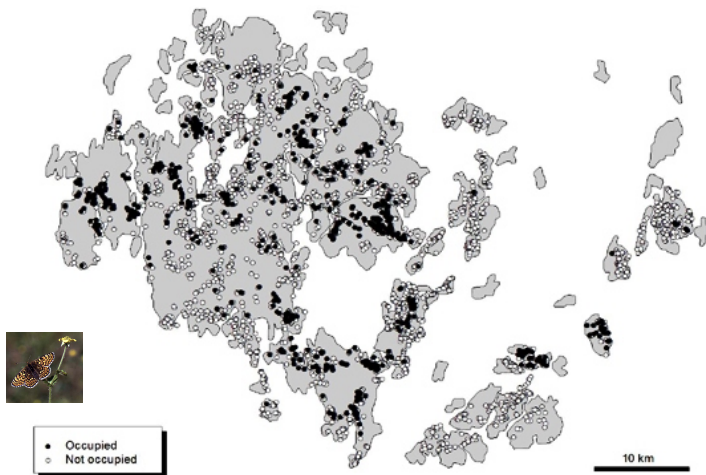
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This particular form is reminiscent of the *Hanski incidence function model*¹, but now there is *no fixed upper limit* on the number of patches that can be occupied.

¹McVinish, R. and Pollett, P.K. (2014) The limiting behaviour of Hanski's incidence function metapopulation model. *J. Appl. Probab.* 51, 297–316.

A famous example (Note: only *known* patches are shown)



Glanville fritillary butterfly (*Melitaea cinxia*) in the Åland Islands in Autumn 2005.

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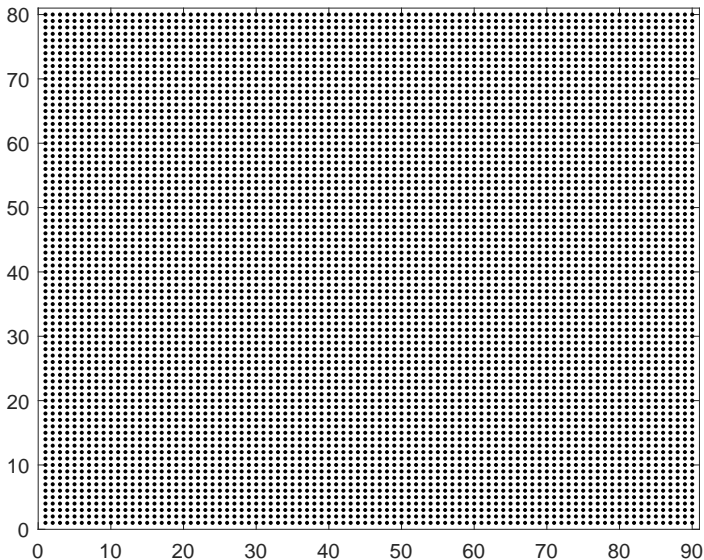
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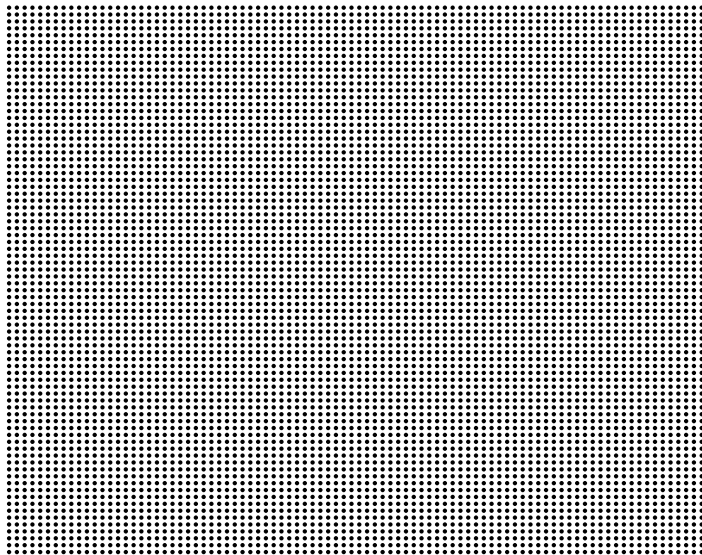
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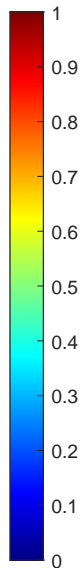
A simulation - patches located on the integer lattice \mathbb{Z}_+^2



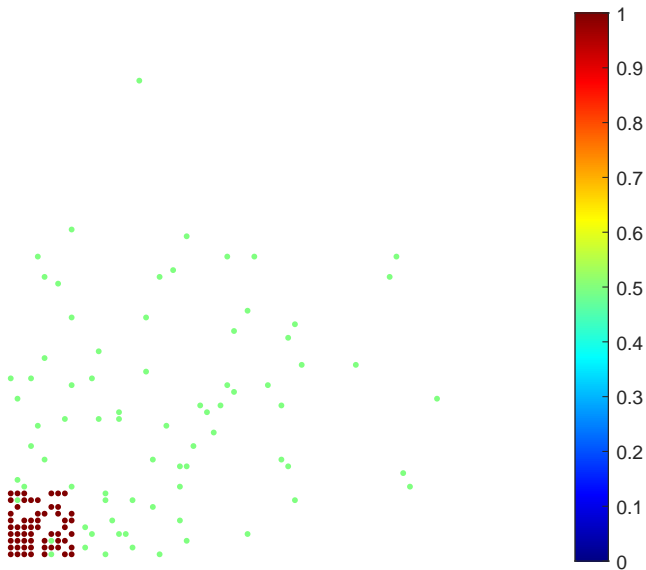
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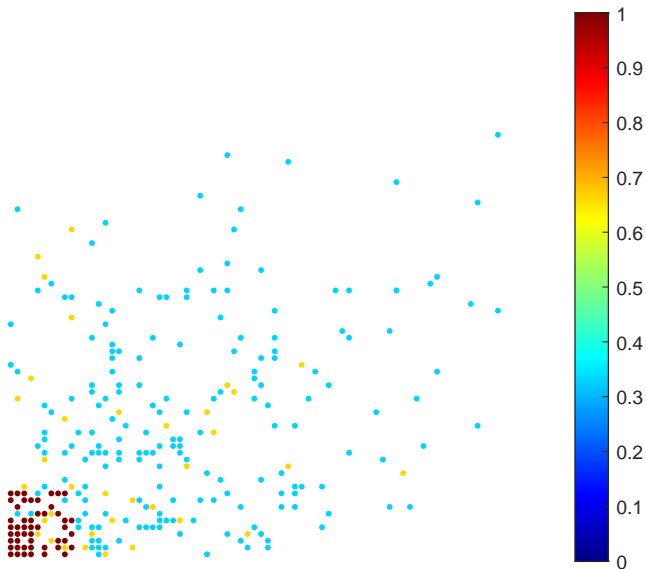
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 0$)



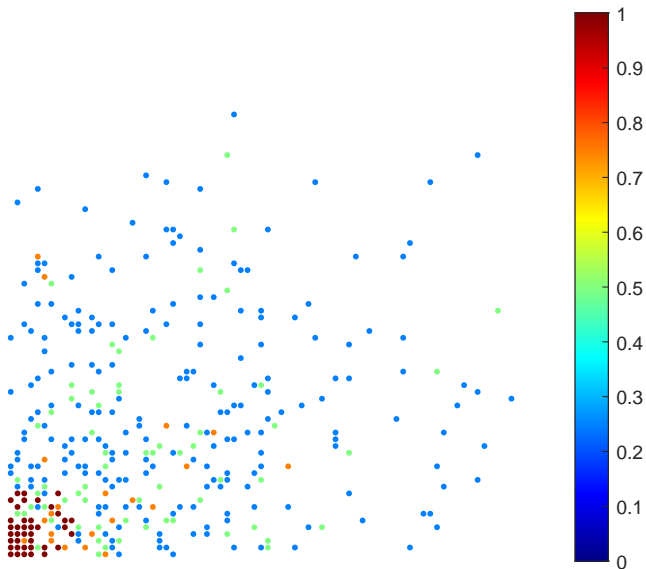
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 1$)



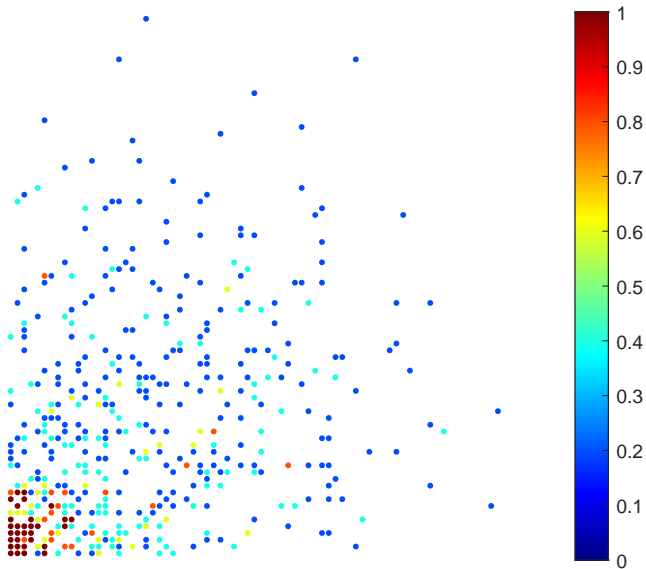
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 2$)



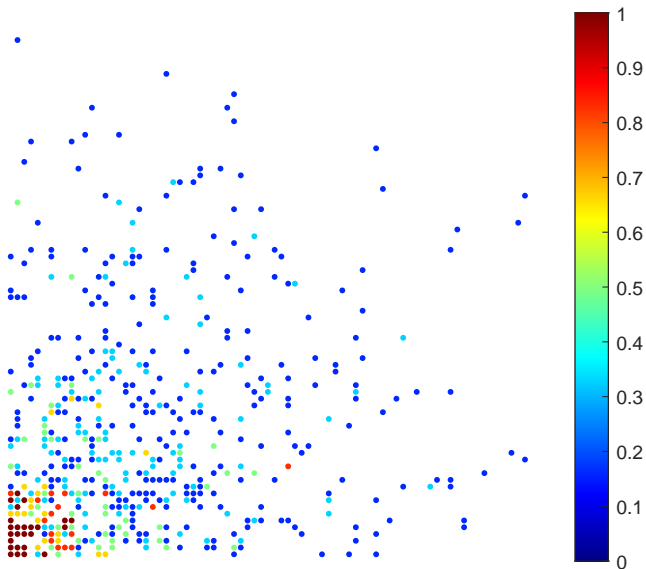
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 3$)



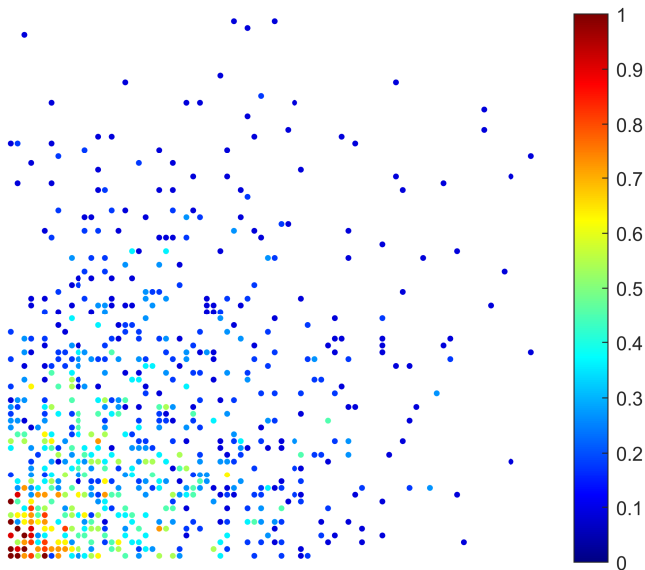
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 4$)



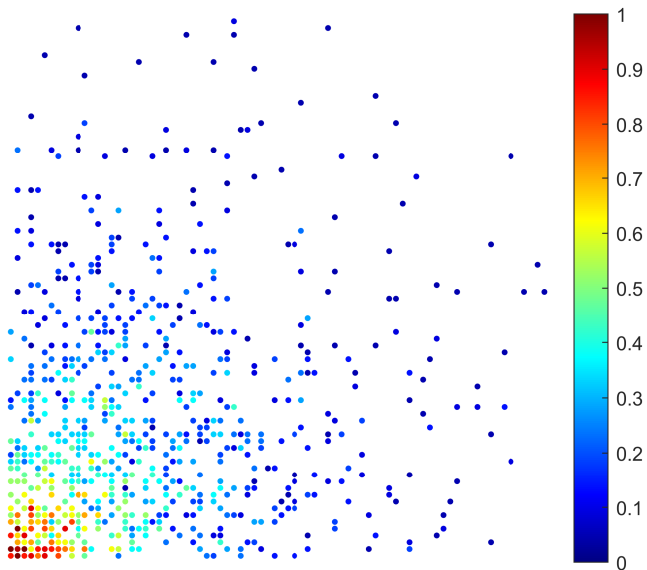
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 5$)



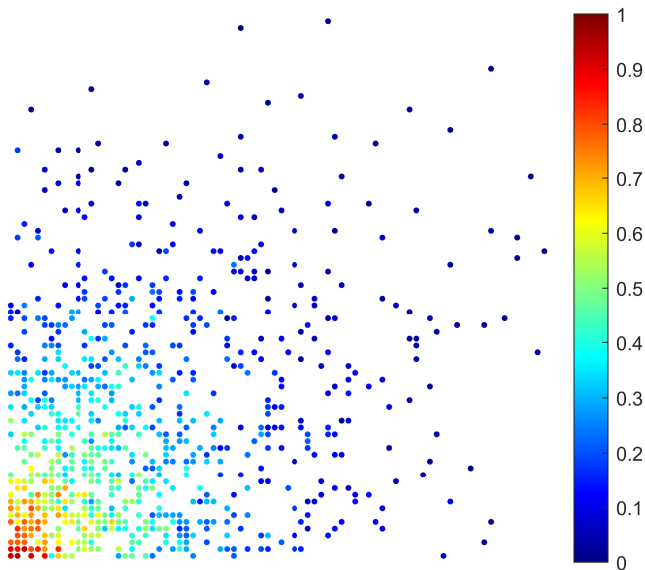
A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 10$)



A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 20$)



A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 50$)



An approximating model

Returning to the general case

$$\mathbb{P}(X_{i,t+1} = 1 | \mathbf{X}_t) = S_i(\mathbf{X}_t)X_{i,t} + C_i(\mathbf{X}_t)(1 - X_{i,t}), \quad i = 1, 2, \dots, \quad t = 0, 1, \dots,$$

we consider a *deterministic analogue*² $\mathbf{p}_t = \{p_{i,t}\}_{i=1}^{\infty}$ that evolves according to

$$p_{i,t+1} = S_i(\mathbf{p}_t)p_{i,t} + C_i(\mathbf{p}_t)(1 - p_{i,t}), \quad i = 1, 2, \dots, \quad t = 0, 1, \dots$$

²Barbour, A.D., McVinish, R. and Pollett, P.K. (2015) Connecting deterministic and stochastic metapopulation models. *J. Math. Biol.* 71, 1481–1504.

(The domains of S_i and C_i have been extended to $[0, 1]^{\mathbb{Z}_+}$.)

The main result

To assess the quality of our approximation, we shall let³

$$\alpha = \sup_{j \in \mathbb{Z}_+} \sum_{i=1}^{\infty} \|\partial_j P_i\|_{\infty} \quad \beta = \sum_{i=1}^{\infty} \left(\sum_{j=1, j \neq i}^{\infty} \|\partial_j P_i\|_{\infty}^2 \right)^{1/2} \quad \gamma = \sum_{i,j=1}^{\infty} \|\partial_j^2 P_i\|_{\infty}$$

and assume these quantities are all finite. Here ∂_j and ∂_j^2 are the first and second partial derivative operators in the j -th coordinate.

³Hodgkinson, L., McVinish, R. and Pollett, P.K. (2020) Normal approximations for discrete-time occupancy processes. *Stochastic Process. Appl.* 130, 6414–6444.

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Theorem 1 There is a constant $C \in (0, 2\sqrt{\pi}]$ such that, for any $\mathbf{w} \in \ell^{\infty}$ and $t \geq 0$,

$$\mathbb{E} \left| \sum_{i=1}^{\infty} w_i (X_{i,t} - p_{i,t}) \right| \leq C \|\mathbf{w}\|_{\infty} (\beta + \gamma) (1 + 2\alpha)^t + \left(\sum_{i=1}^{\infty} w_i^2 p_{i,t} \right)^{1/2}.$$

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The metapopulation model

In our metapopulation model

$$P_i(\mathbf{x}) := s_i x_i + f \left(a_i \sum_j d_{ij} x_j \right) (1 - x_i), \quad \mathbf{x} \in [0, 1]^{\mathbb{Z}_+}.$$

Recall that s_i is the patch i survival probability, a_i is the patch weight, d_{ij} is the migration potential from patch j to patch i , and $f : [0, \infty) \rightarrow [0, 1]$, the colonisation function, satisfies $f(0) = 0$.

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Now assume that $\sum_i a_i < +\infty$ (the total weight of all patches is finite), and suppose that $d_{ij} = D(\mathbf{z}_i, \mathbf{z}_j) := \kappa(\|\mathbf{z}_i - \mathbf{z}_j\|)$, for patches located at points $\{\mathbf{z}_i\}$ in \mathbb{R}^d , where κ is a smooth, non-negative, monotone decreasing function (typically $\kappa(x) = e^{-\psi x}$, or $\kappa(x) = e^{-\psi x^2}$, $\psi > 0$). These assumptions are enough to ensure that α, β, γ are all finite.

The metapopulation model - a high density limit

We shall suppose that the patch locations are spaced according to some measure σ . In particular, for any bounded continuous function g ,

$$\frac{1}{m^d} \sum_{i=1}^{\infty} g(m^{-1}z_i) \rightarrow \int_{\mathbb{R}^d} g(z)\sigma(dz), \quad \text{as } m \rightarrow \infty.$$

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Suppose that there is a sequence of models $\{\mathbf{X}_t^{(m)}\}_{m=1}^{\infty}$ with parameters $s_i^{(m)}$, $a_i^{(m)}$, $d_{ij}^{(m)}$, and the same colonisation function f , such that

$$s_i^{(m)} = s(m^{-1}z_i), \quad a_i^{(m)} = a(m^{-1}z_i), \quad d_{ij}^{(m)} = m^{-d} \kappa(m^{-1}\|z_i - z_j\|),$$

for smooth functions $\kappa : \mathbb{R}_+ \rightarrow \mathbb{R}_+$, $a : \mathbb{R}^d \rightarrow \mathbb{R}_+$, and $s : \mathbb{R}^d \rightarrow [0, 1]$.

In this way, the patch locations are effectively being drawn together as $m \rightarrow \infty$.

The metapopulation model - a high density limit

To cut a long story short, we use the earlier result,

$$\mathbb{E} \left| \sum_{i=1}^{\infty} w_i (X_{i,t} - p_{i,t}) \right| \leq C \|\mathbf{w}\|_{\infty} (\beta + \gamma) (1 + 2\alpha)^t + \left(\sum_{i=1}^{\infty} w_i^2 p_{i,t} \right)^{1/2},$$

to compare the finite measure $\pi_t^{(m)}$ defined by

$$\pi_t^{(m)}(B) = m^{-d} \sum_{i=1}^{\infty} p_{i,t}^{(m)} \mathbb{1}\{m^{-1}z_i \in B\}, \quad B \in \mathcal{B}(\mathbb{R}^d),$$

with the *random measure* $\mu_t^{(m)}$ defined by

$$\mu_t^{(m)}(B) = m^{-d} \sum_{i=1}^{\infty} X_{i,t}^{(m)} \mathbb{1}\{m^{-1}z_i \in B\}, \quad B \in \mathcal{B}(\mathbb{R}^d).$$

We prove that, as $m \rightarrow \infty$, $\int g(z) \mu_t^{(m)}(dz) \rightarrow \int g(z) p_t(z) \sigma(dz)$, for some function p_t . In particular, the functions p_t , $t = 0, 1, \dots$, satisfy the recursion

$$p_{t+1}(z) = s(z) p_t(z) + (1 - p_t(z)) f \left(a(z) \int \kappa(\|z - x\|) p_t(x) \sigma(dz) \right), \quad z \in \mathbb{R}^d.$$

Nice interpretation: if a patch is located at z , $p_t(z)$ is the chance it is occupied.



The earlier simulation - patches located on the integer lattice \mathbb{Z}_+^2

Details

$$d = 2$$

Colonisation function: $f(x) = 1 - \exp(-\alpha x)$ with $\alpha = 0.01$.

Survival function: $s(\mathbf{z}) = \exp(-\phi \|\mathbf{z}\|)$ with $\phi = 0.25$.

Patch weight function: $a(\mathbf{z}) = \exp(-\theta \|\mathbf{z}\|)$ with $\theta = 0.25$.

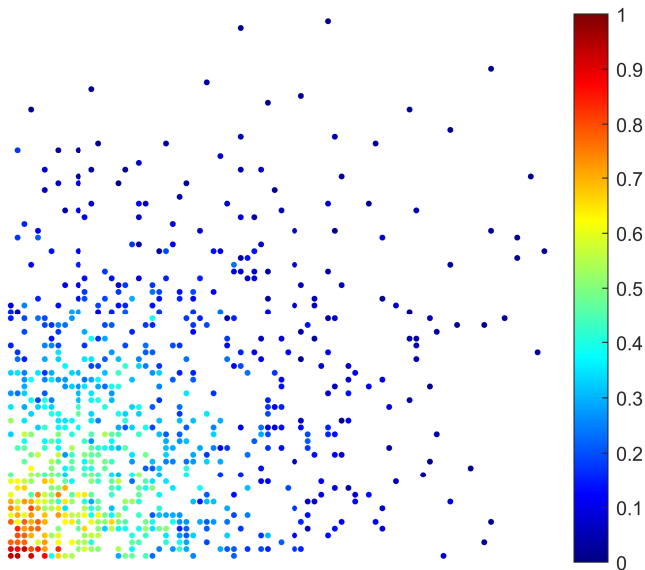
Easy of movement function: $d(\mathbf{x}, \mathbf{z}) = b \exp(-\psi \|\mathbf{x} - \mathbf{z}\|)$ with $b = 25$ and $\psi = 0.4$.

Scaling: $m = 8$

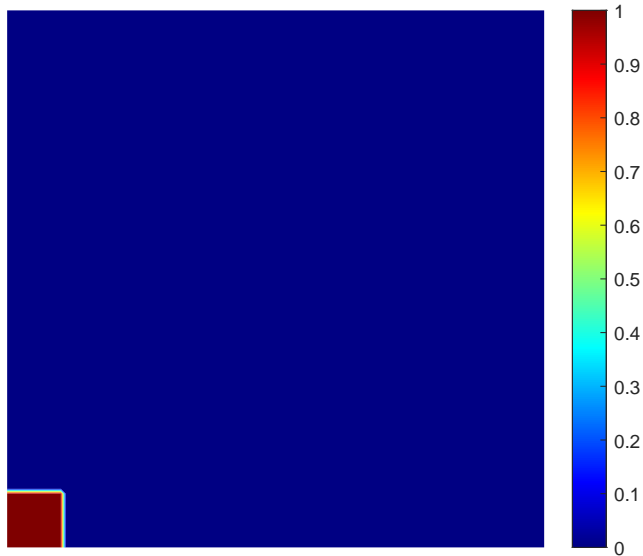
$$s_i^{(m)} = s(m^{-1}z_i), \quad a_i^{(m)} = a(m^{-1}z_i), \quad d_{ij}^{(m)} = m^{-2} \kappa(m^{-1} \|z_i - z_j\|)$$

Initially configuration: 70 percent of patches are occupied in $\{1, 2, \dots, 10\}^2$.

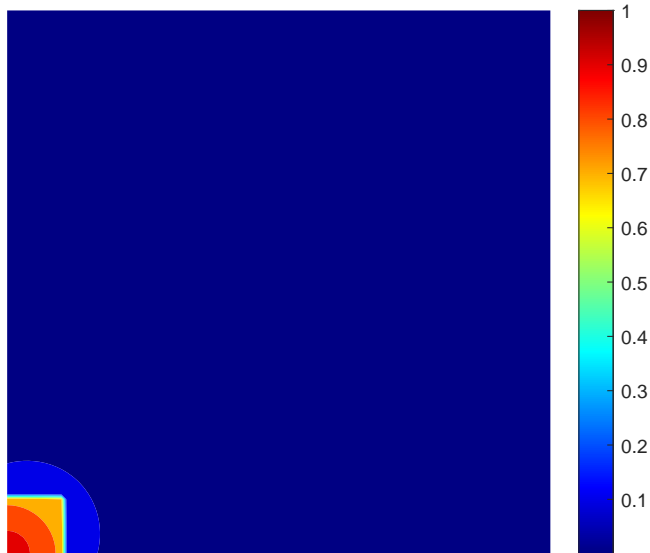
The earlier simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 50$)



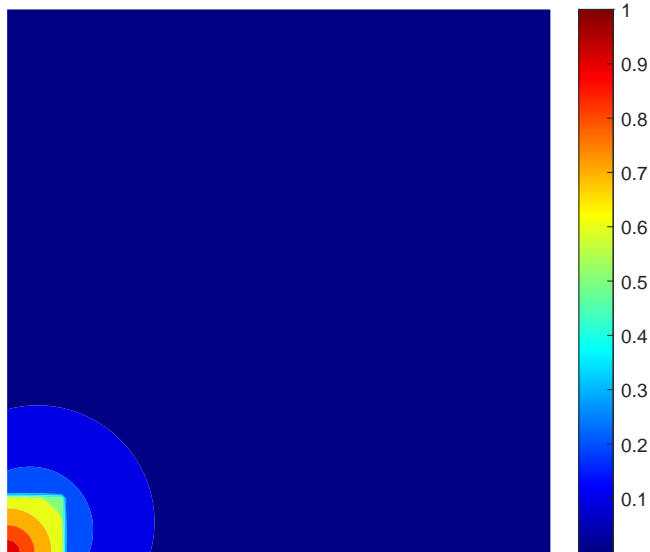
Occupancy probability heatmap $p_t(z)$ ($t = 0$)



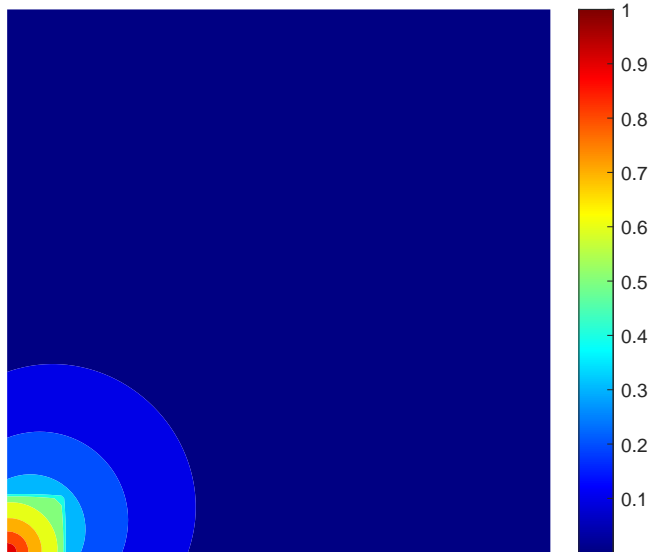
Occupancy probability heatmap $p_t(z)$ ($t = 1$)



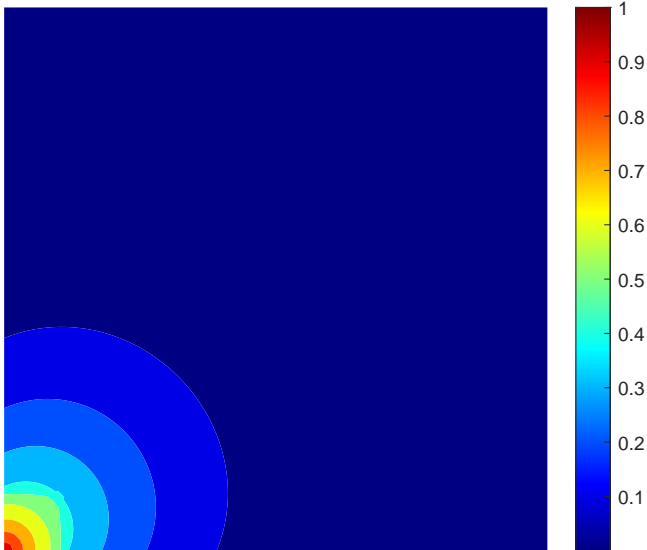
Occupancy probability heatmap $p_t(z)$ ($t = 2$)



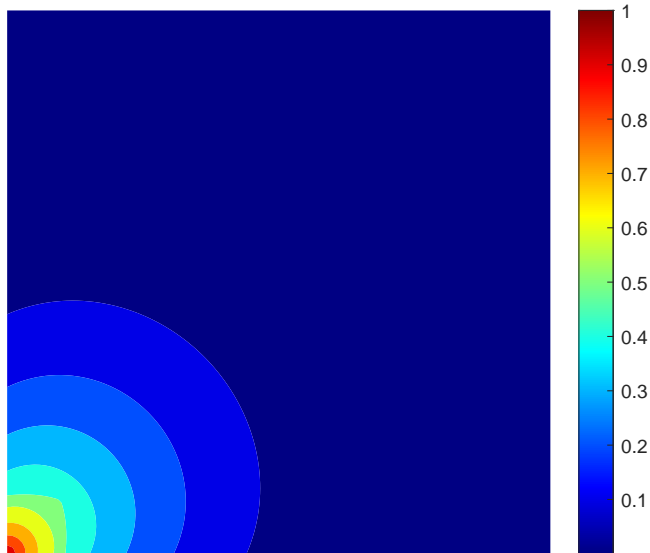
Occupancy probability heatmap $p_t(z)$ ($t = 3$)



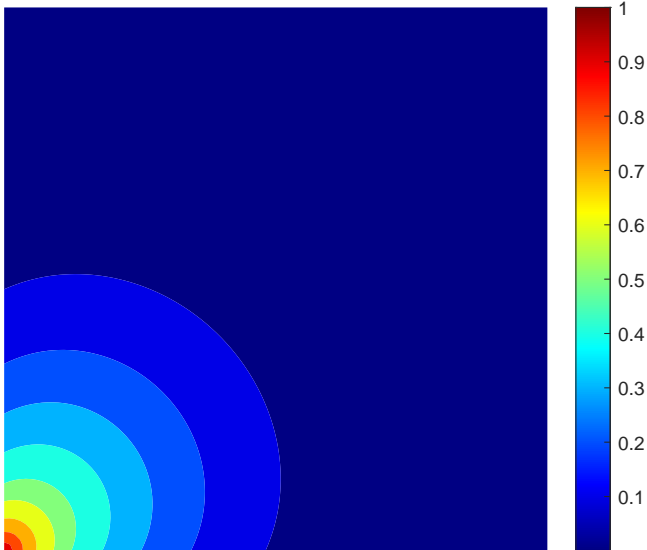
Occupancy probability heatmap $p_t(z)$ ($t = 4$)



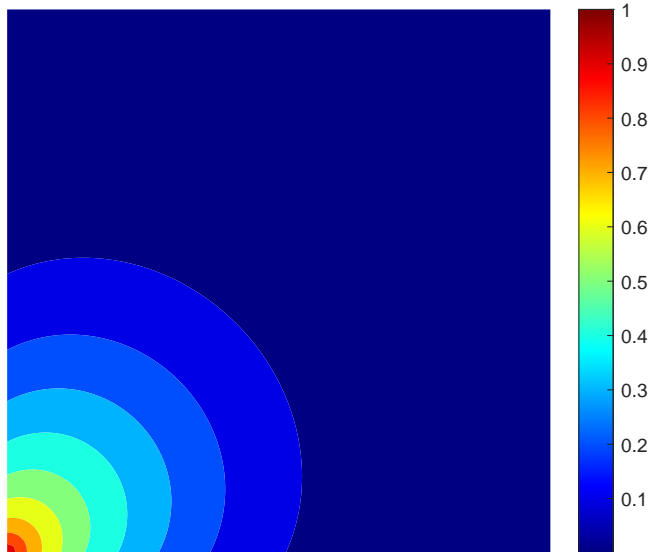
Occupancy probability heatmap $p_t(z)$ ($t = 5$)



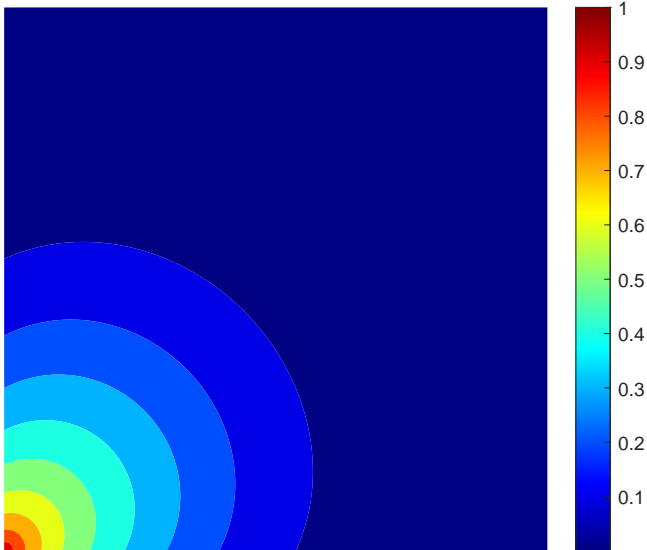
Occupancy probability heatmap $p_t(z)$ ($t = 6$)



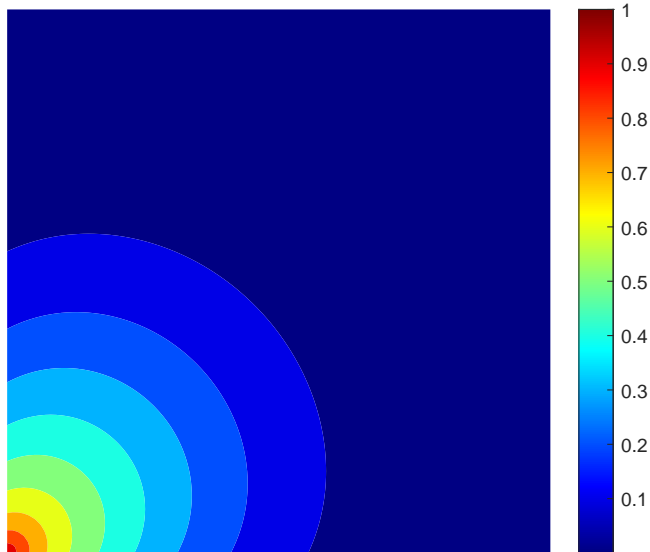
Occupancy probability heatmap $p_t(z)$ ($t = 7$)



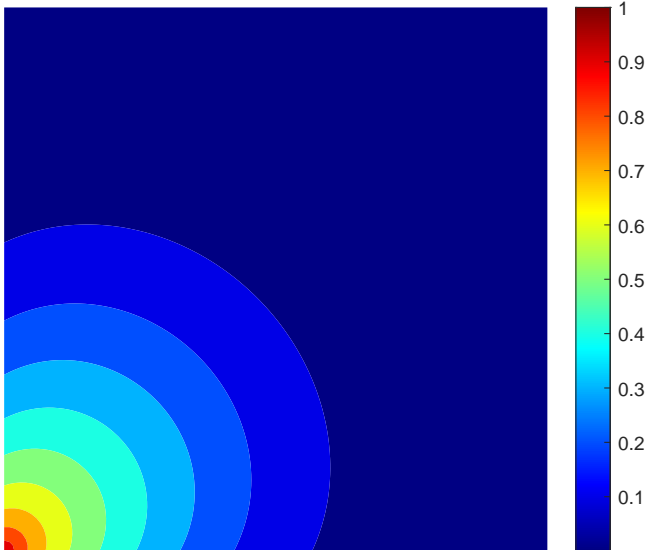
Occupancy probability heatmap $p_t(z)$ ($t = 8$)



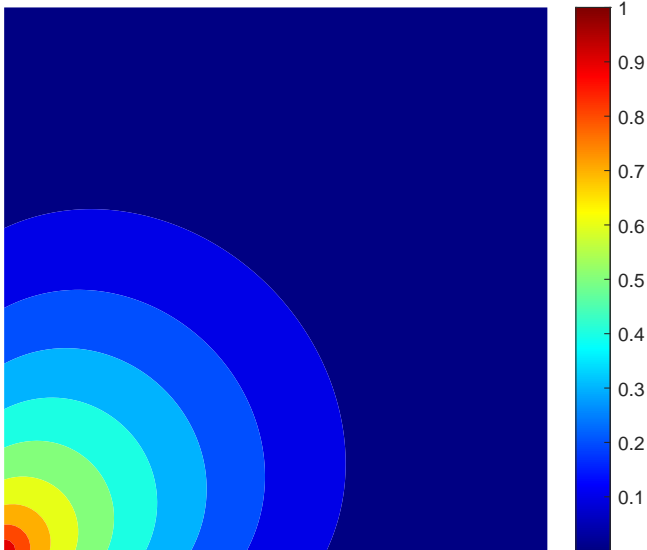
Occupancy probability heatmap $p_t(z)$ ($t = 9$)



Occupancy probability heatmap $p_t(z)$ ($t = 10$)



Occupancy probability heatmap $p_t(z)$ ($t = 50$)



A simulation - patches located on the integer lattice \mathbb{Z}_+^2 ($t = 50$)

